

6.819/6.869 Advances in Computer Vision

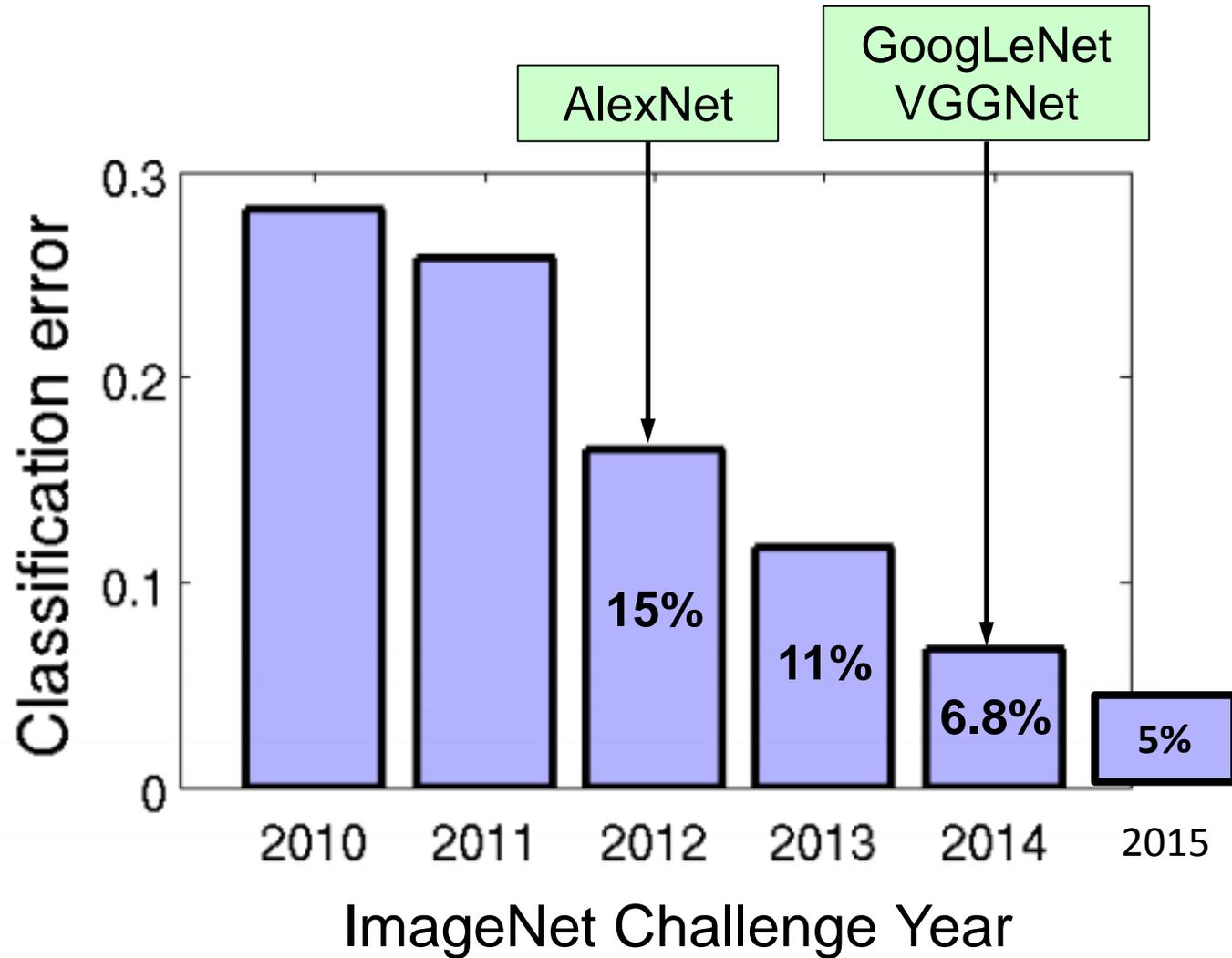


Aditya Khosla

Today's class

- Part 1: From state-of-the-art to state-of-the-artest
 - Fine-tuning
 - Data augmentation
- Part 2: Applications
 - Detection, segmentation, ...
- Part 3: Learning sequences
 - RNNs/LSTMs

Object recognition

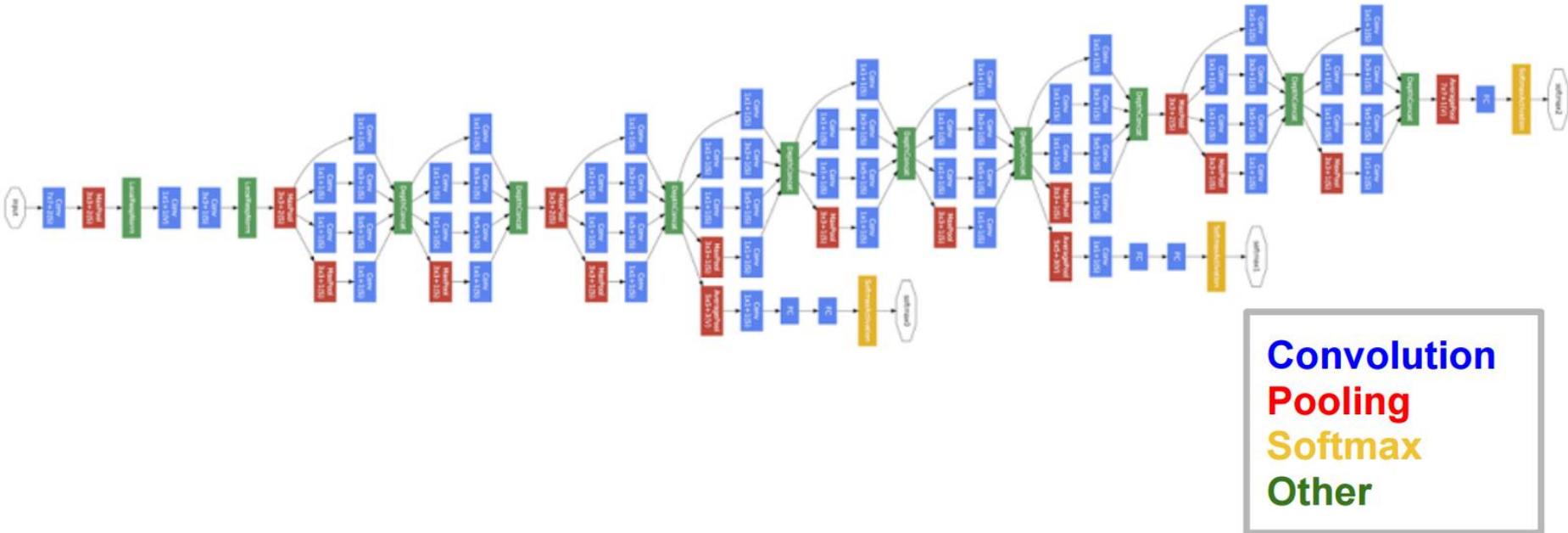


A close-up shot of Leonardo DiCaprio in a dark suit, white shirt, and patterned tie. He has a serious, intense expression and is looking slightly to his right. The lighting is warm and dramatic, typical of a movie scene. Another person's head and shoulder are visible in the foreground on the right, partially obscuring the view.

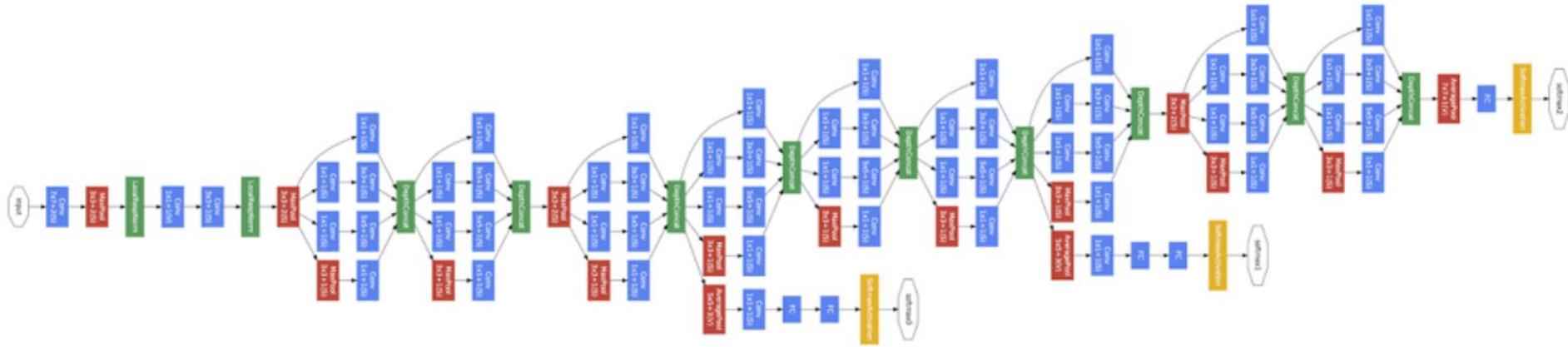
WE NEED TO GO

DEEPER

GoogLeNet



GoogLeNet vs AlexNet

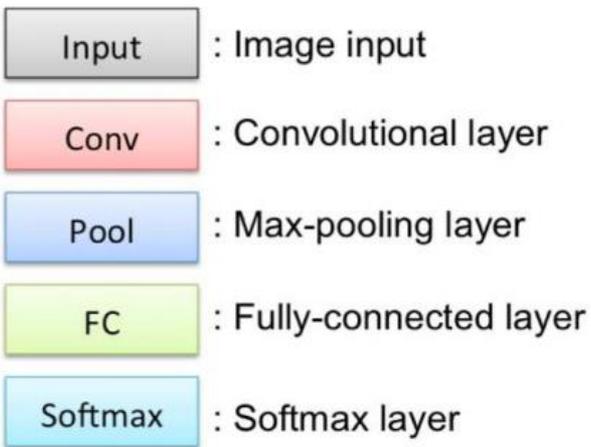


GoogLeNet

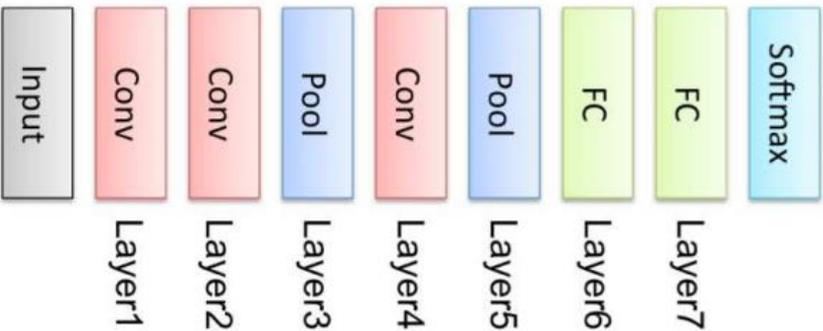


AlexNet

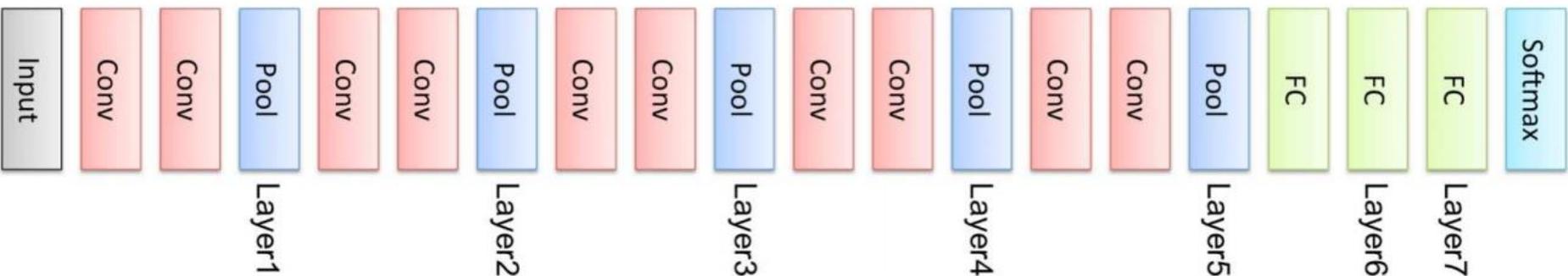
Convolution
Pooling
Softmax
Other



AlexNet



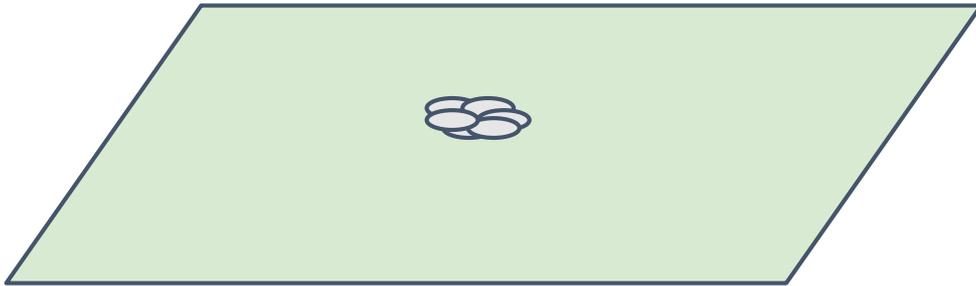
VGGNet



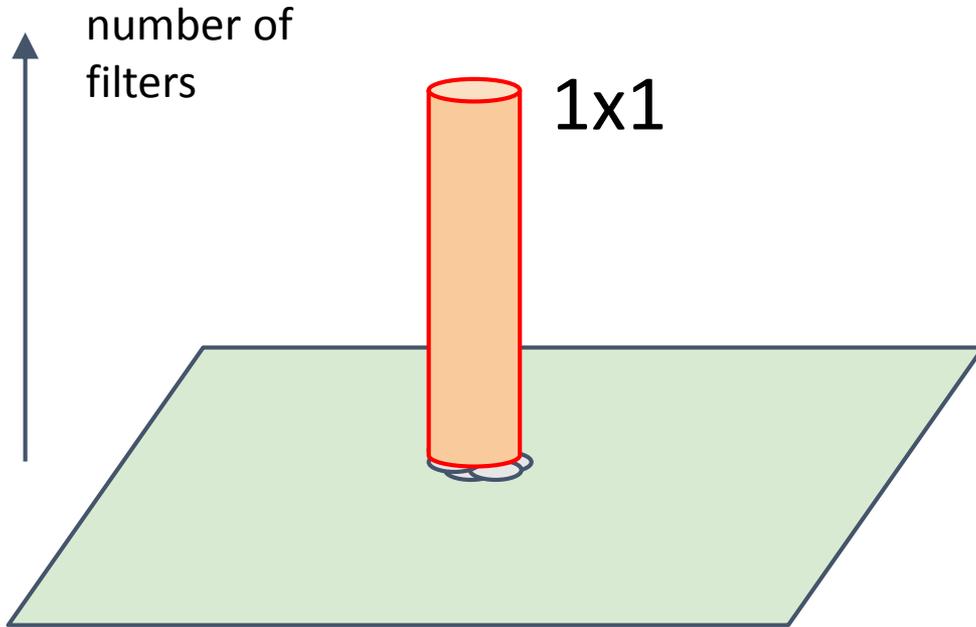
GoogLeNet

- Power and Memory use considerations are important for practical use.
- Image data is mostly sparse and clustered.
- Hebbian Principle:
“Neurons that fire together, wire together”

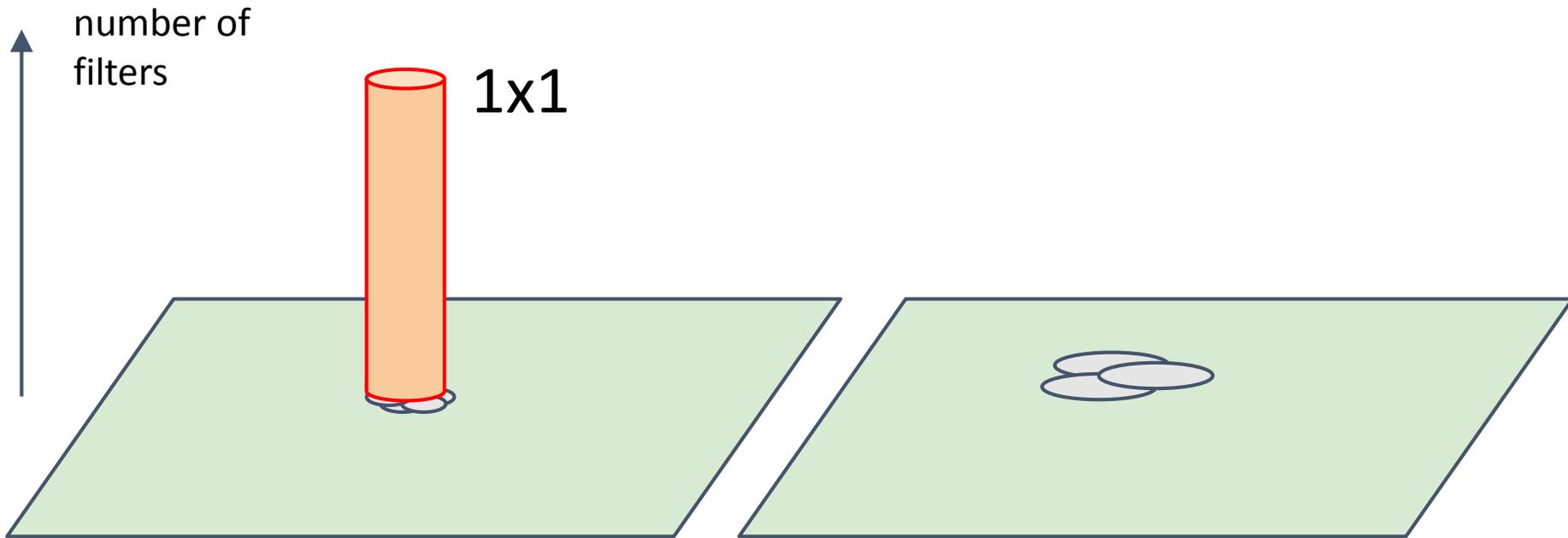
In images, correlations tend to be local



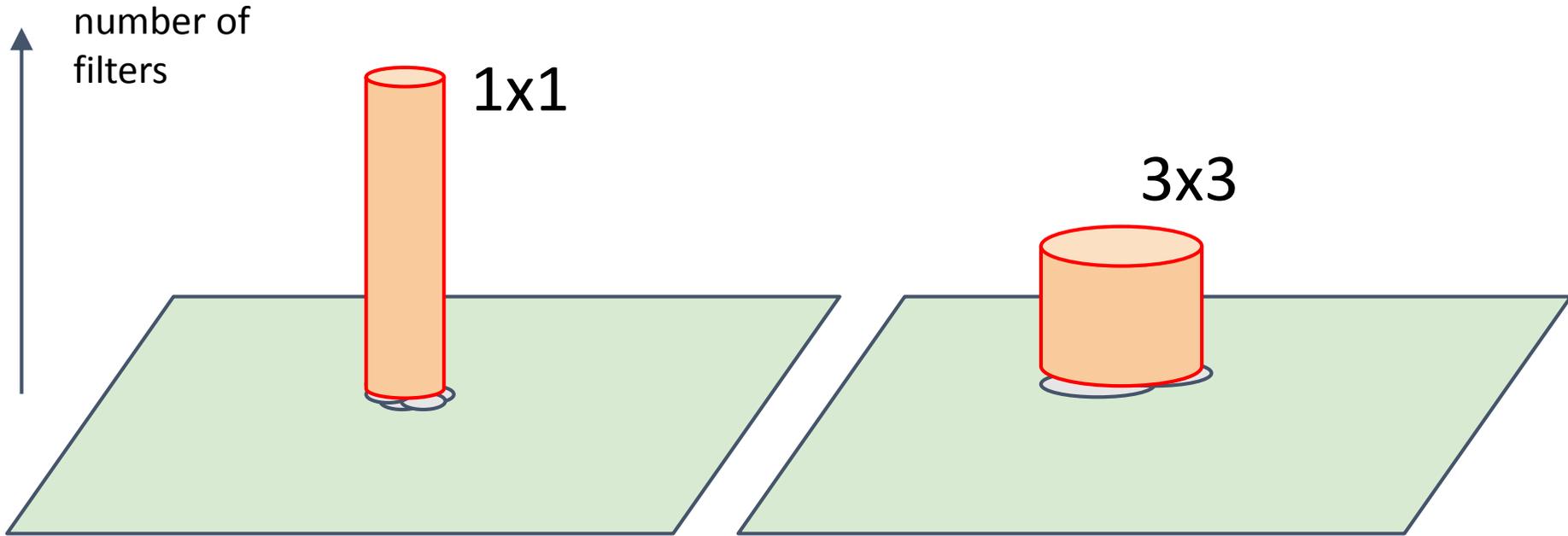
Cover very local clusters by 1x1 convolutions



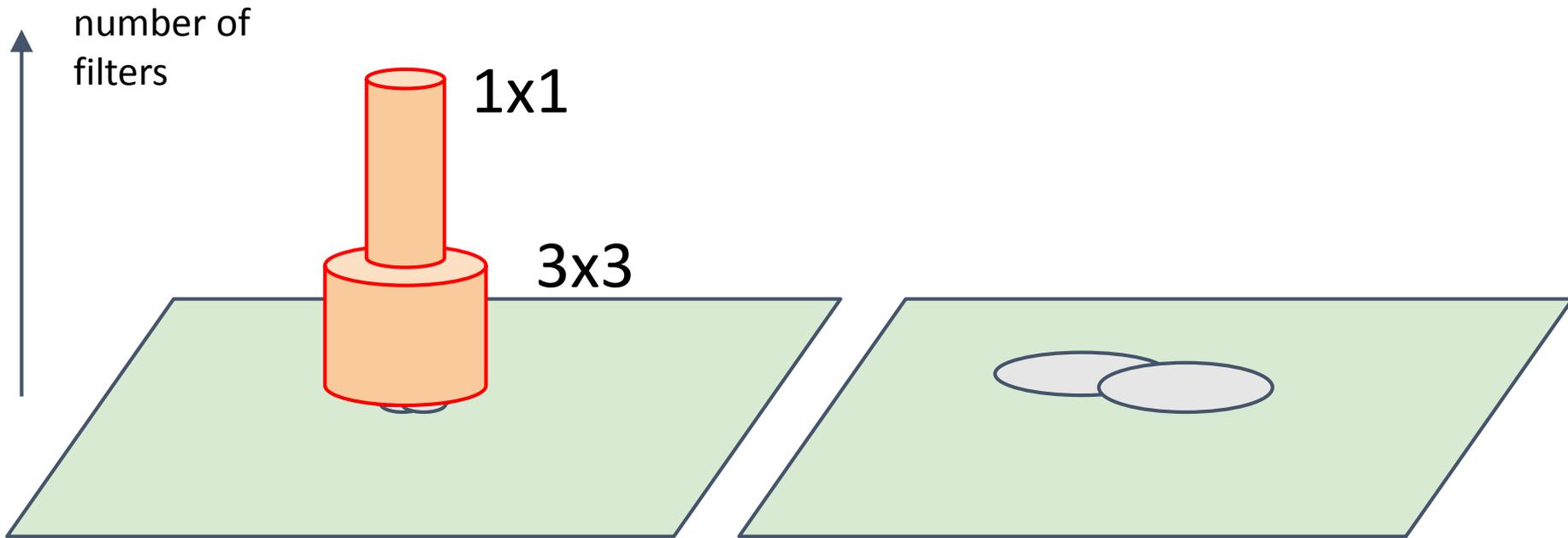
Less spread out correlations



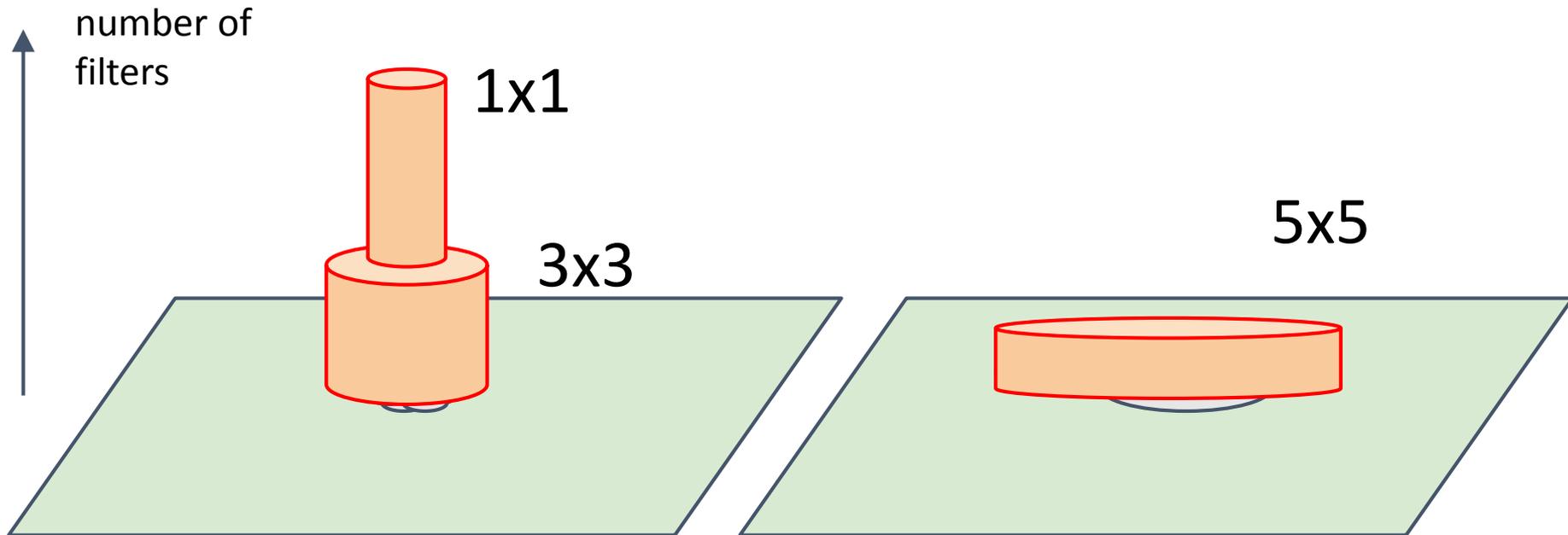
Cover more spread out clusters by 3x3 convolutions



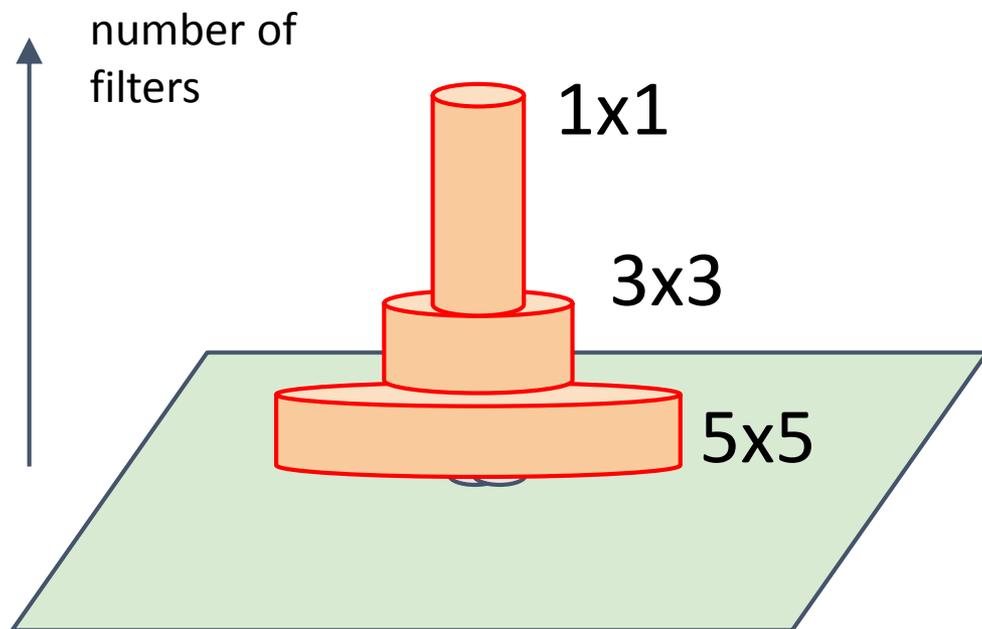
Cover more spread out clusters by 5x5 convolutions



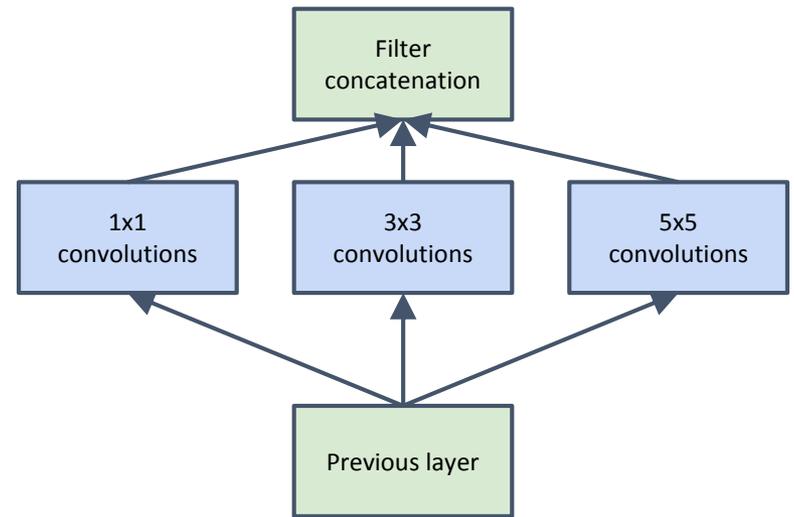
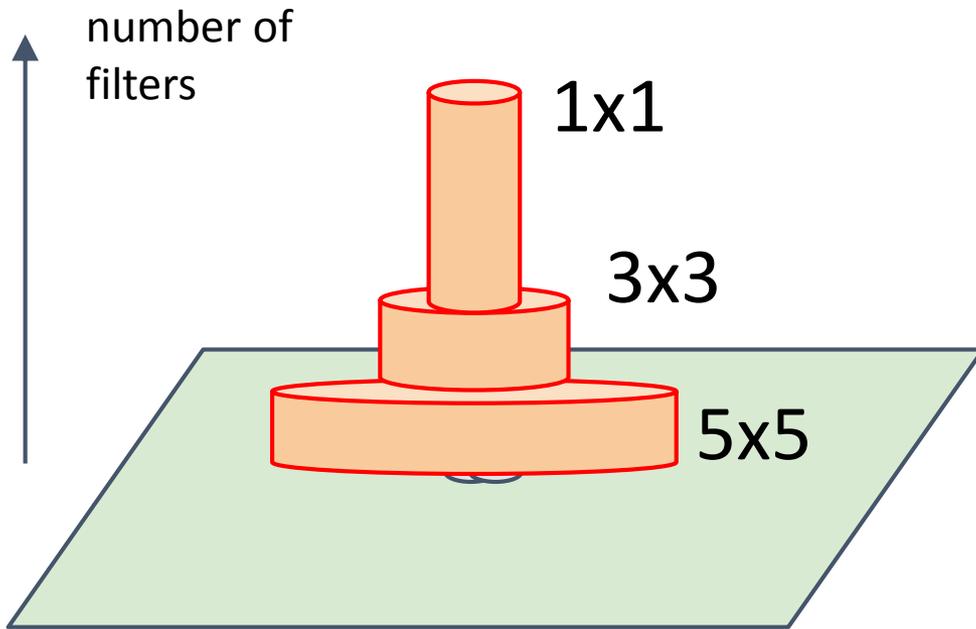
Cover more spread out clusters by 5x5 convolutions



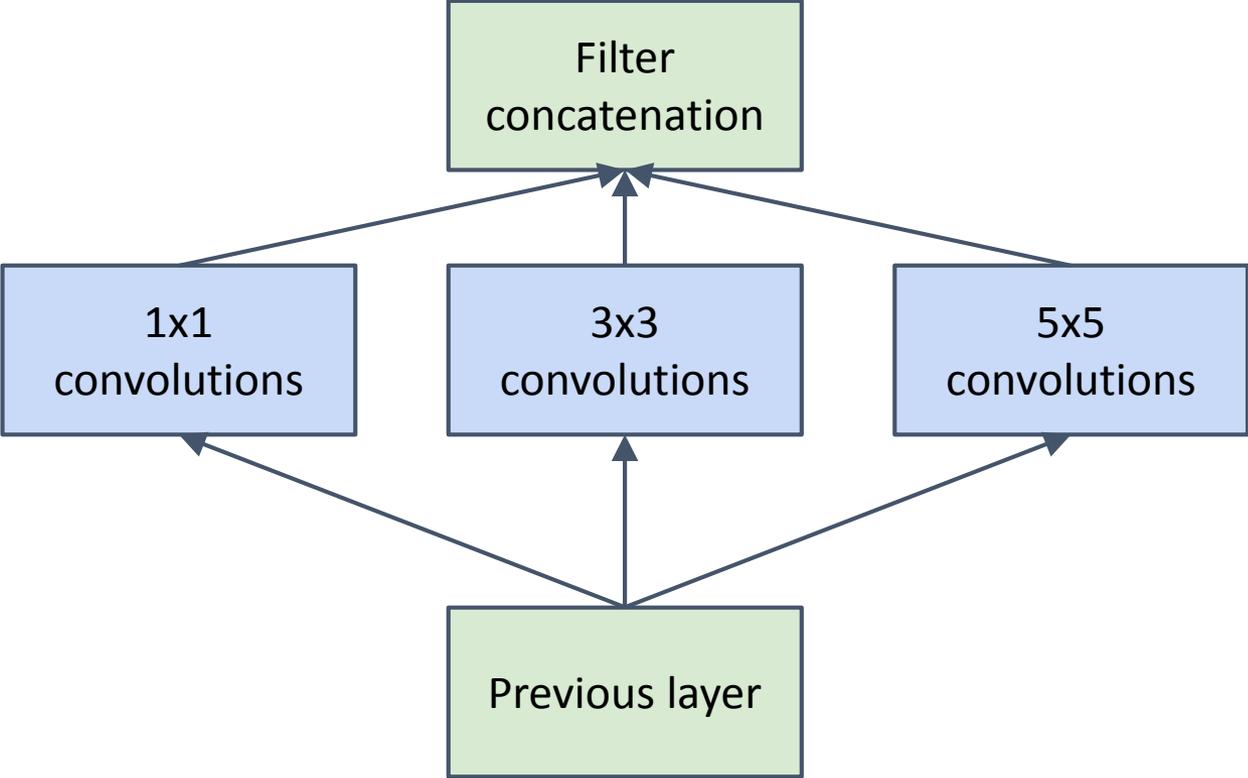
A heterogeneous set of convolutions



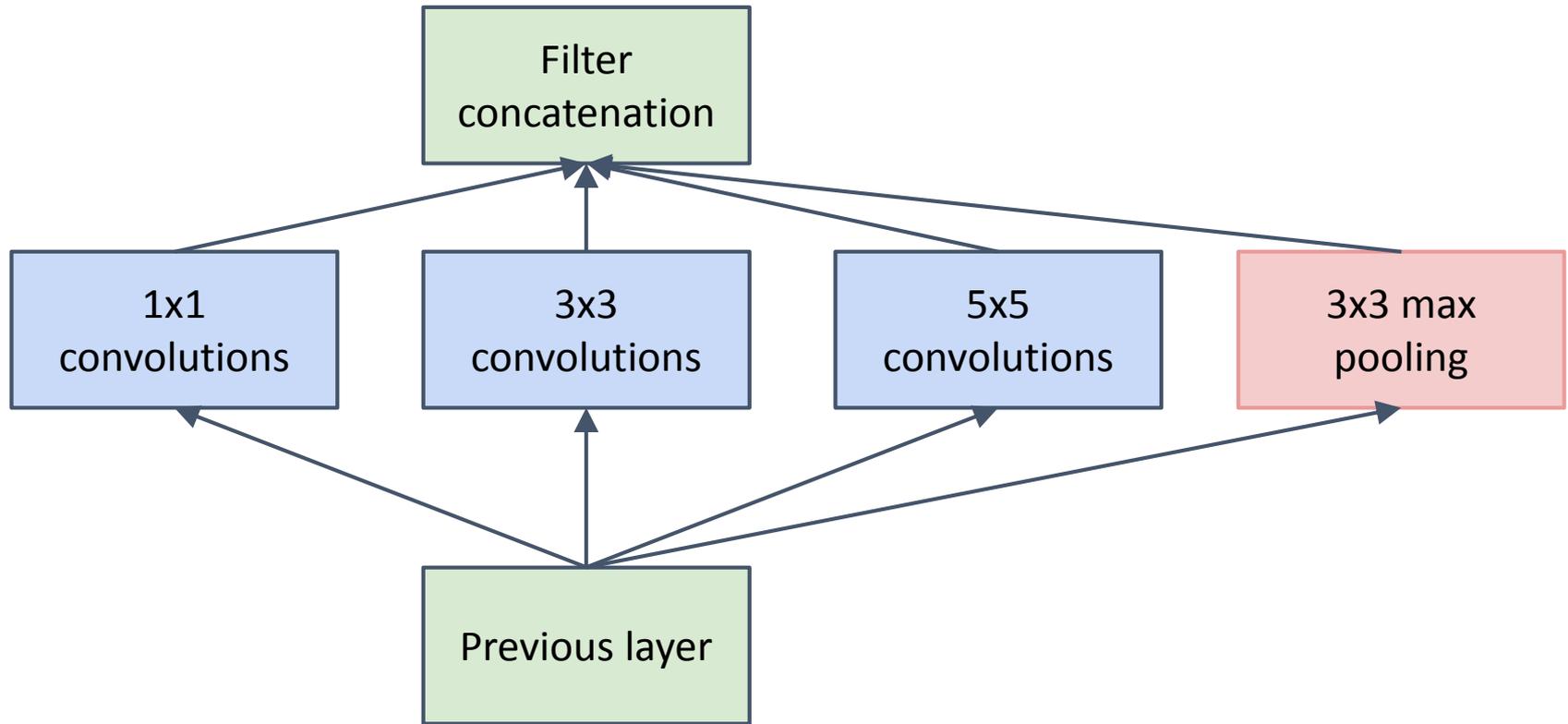
Schematic view (naive version)



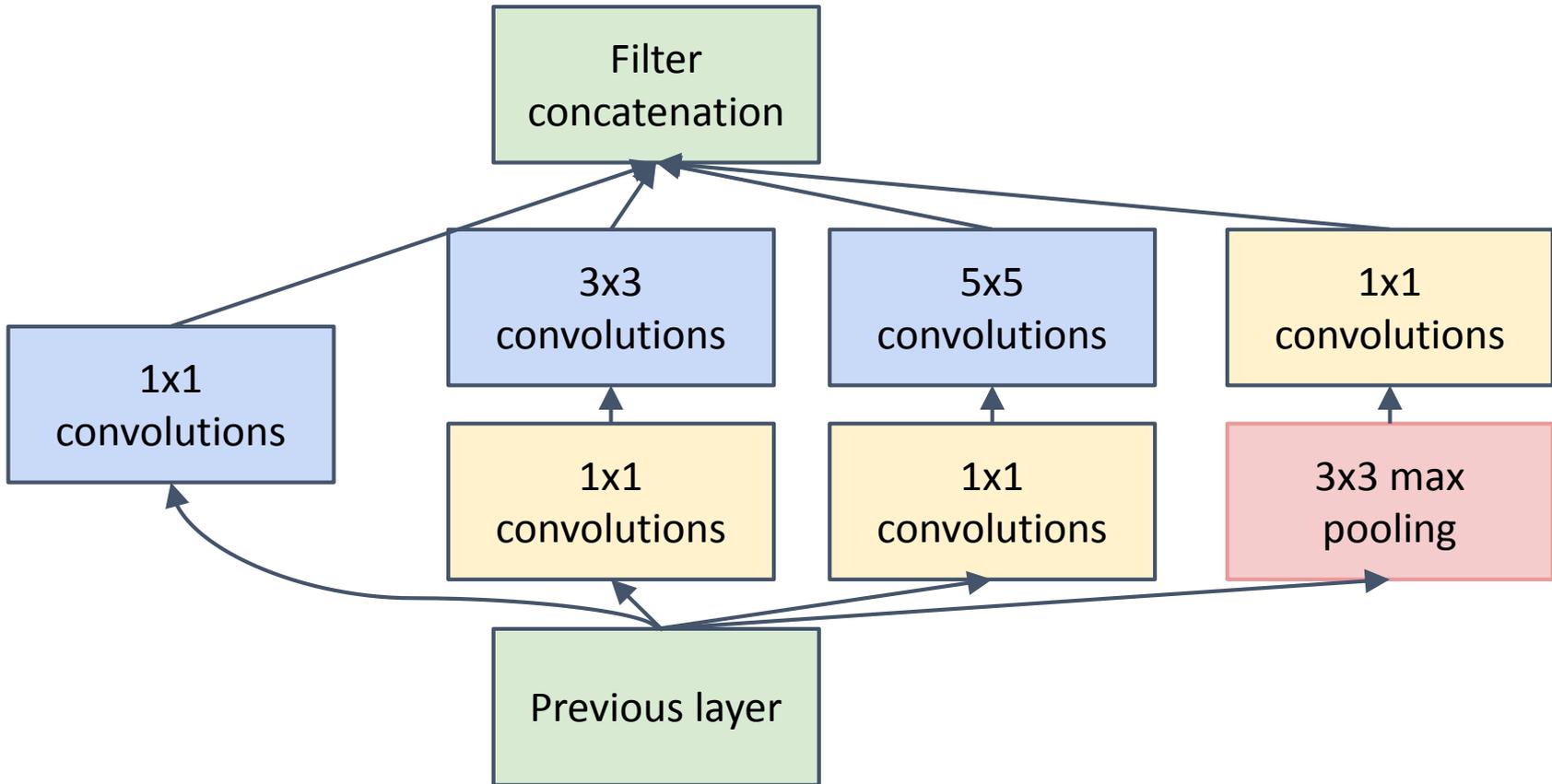
Naive idea



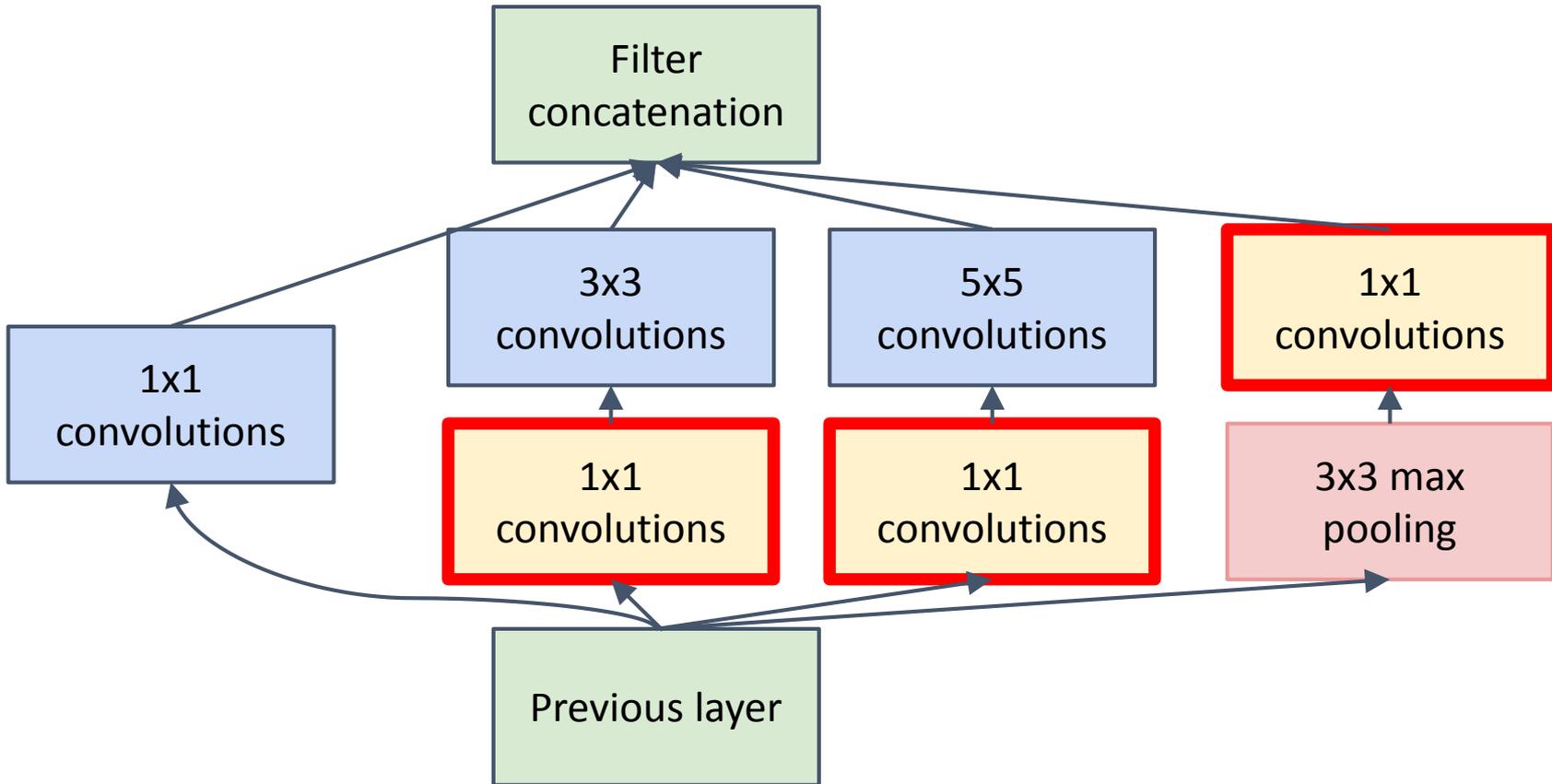
Naive idea (**does not work!**)



Inception module

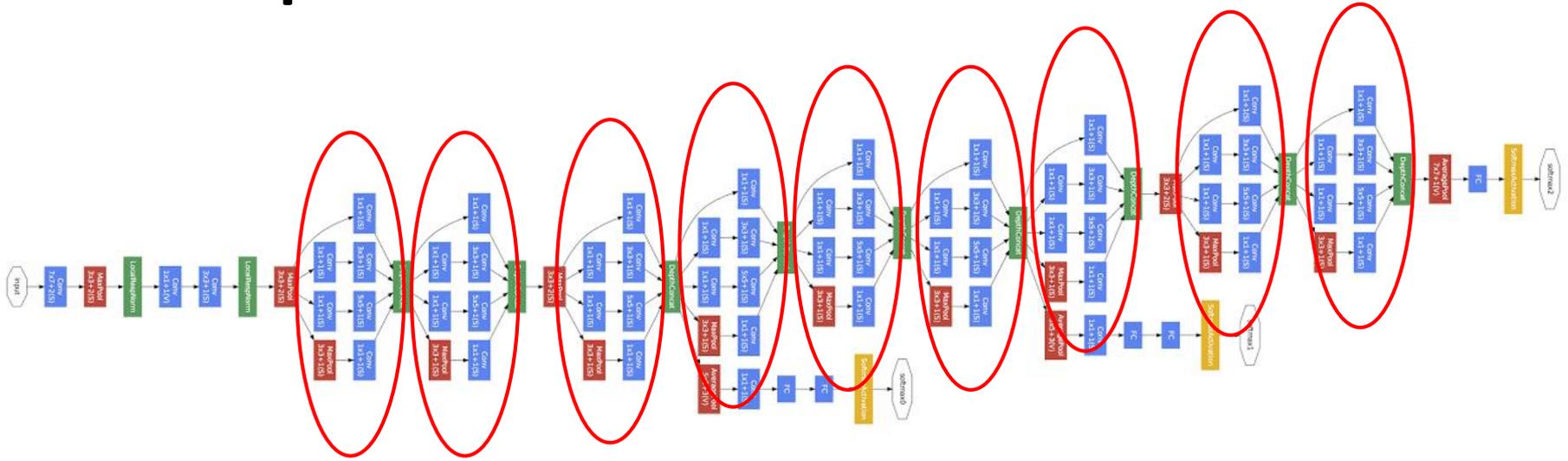


Inception module



Dimensionality reduction!

Inception



9 **Inception** modules

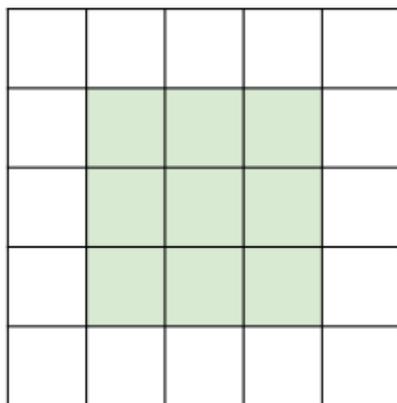
Convolution
Pooling
Softmax
Other

The power of small filters

(and stride 1)

Suppose we stack two CONV layers with receptive field size 3x3
=> Each neuron in 1st CONV sees a 3x3 region of input.

1st CONV neuron
view of the input:

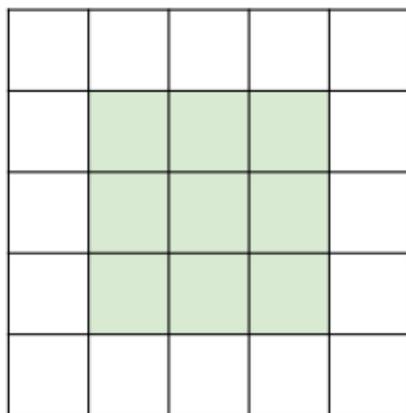


The power of small filters

Suppose we stack two CONV layers with receptive field size 3×3
=> Each neuron in 1st CONV sees a 3×3 region of input.

Q: What region of input does each neuron in 2nd CONV see?

2nd CONV neuron
view of 1st conv:

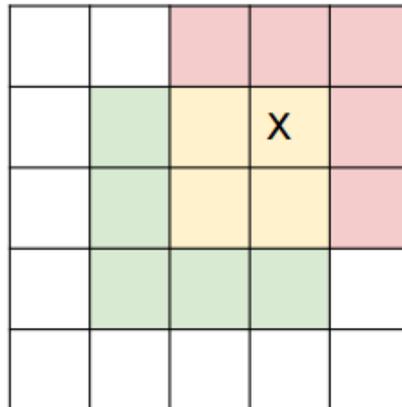


The power of small filters

Suppose we stack two CONV layers with receptive field size 3×3
=> Each neuron in 1st CONV sees a 3×3 region of input.

Q: What region of input does each neuron in 2nd CONV see?

2nd CONV neuron
view of input:



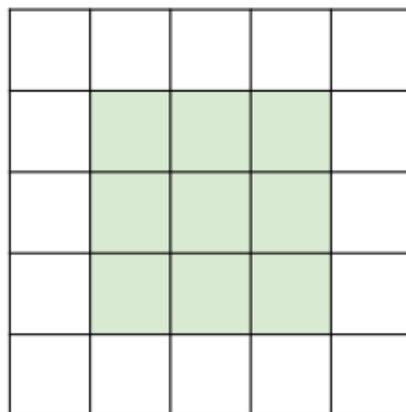
Answer: $[5 \times 5]$

The power of small filters

Suppose we stack **three** CONV layers with receptive field size 3x3

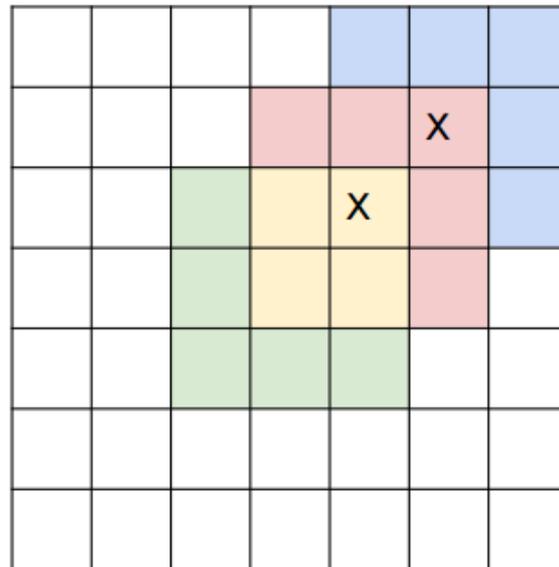
Q: What region of input does each neuron in 3rd CONV see?

3rd CONV neuron
view of 2nd CONV:



The power of small filters

Suppose we stack **three** CONV layers with receptive field size 3x3
Q: What region of input does each neuron in 3rd CONV see?



Answer: [7x7]

The power of small filters

Suppose input has depth C & we want output depth C as well

1x CONV with 7x7 filters

Number of weights:

$$\begin{aligned} & C \cdot (7 \cdot 7 \cdot C) \\ & = \mathbf{49 C^2} \end{aligned}$$

3x CONV with 3x3 filters

Number of weights:

$$\begin{aligned} & C \cdot (3 \cdot 3 \cdot C) + C \cdot (3 \cdot 3 \cdot C) + C \cdot (3 \cdot 3 \cdot C) \\ & = 3 \cdot 9 \cdot C^2 \\ & = \mathbf{27 C^2} \end{aligned}$$

VGGnet

[Very Deep Convolutional Networks for Large-Scale Image Recognition, Simonyan et al., 2014]

ConvNet Configuration					
A	A-LRN	B	C	D	E
11 weight layers	11 weight layers	13 weight layers	16 weight layers	16 weight layers	19 weight layers
input (224 × 224 RGB image)					
conv3-64	conv3-64 LRN	conv3-64 conv3-64	conv3-64 conv3-64	conv3-64 conv3-64	conv3-64 conv3-64
maxpool					
conv3-128	conv3-128	conv3-128 conv3-128	conv3-128 conv3-128	conv3-128 conv3-128	conv3-128 conv3-128
maxpool					
conv3-256 conv3-256	conv3-256 conv3-256	conv3-256 conv3-256 conv1-256	conv3-256 conv3-256 conv1-256	conv3-256 conv3-256 conv3-256	conv3-256 conv3-256 conv3-256
maxpool					
conv3-512 conv3-512	conv3-512 conv3-512	conv3-512 conv3-512	conv3-512 conv3-512 conv1-512	conv3-512 conv3-512 conv3-512	conv3-512 conv3-512 conv3-512 conv3-512
maxpool					
conv3-512 conv3-512	conv3-512 conv3-512	conv3-512 conv3-512	conv3-512 conv3-512 conv1-512	conv3-512 conv3-512 conv3-512	conv3-512 conv3-512 conv3-512 conv3-512
maxpool					
FC-4096					
FC-4096					
FC-1000					
soft-max					

ConvNet config. (Table 1)	smallest image side		top-1 val. error (%)	top-5 val. error (%)
	train (S)	test (Q)		
A	256	256	29.6	10.4
A-LRN	256	256	29.7	10.5
B	256	256	28.7	9.9
C	256	256	28.1	9.4
	384	384	28.1	9.3
	[256;512]	384	27.3	8.8
D	256	256	27.0	8.8
	384	384	26.8	8.7
	[256;512]	384	25.6	8.1
E	256	256	27.3	9.0
	384	384	26.9	8.7
	[256;512]	384	25.5	8.0

=> Evidence that using 3x3 instead of 1x1 works better

Table 2: Number of parameters (in millions).

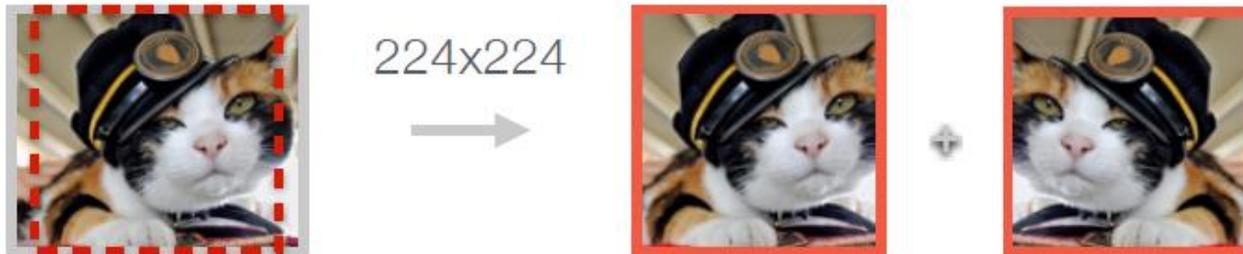
Network	A,A-LRN	B	C	D	E
Number of parameters	133	133	134	138	144

Data augmentation

a. No augmentation (= 1 image)



b. Flip augmentation (= 2 images)

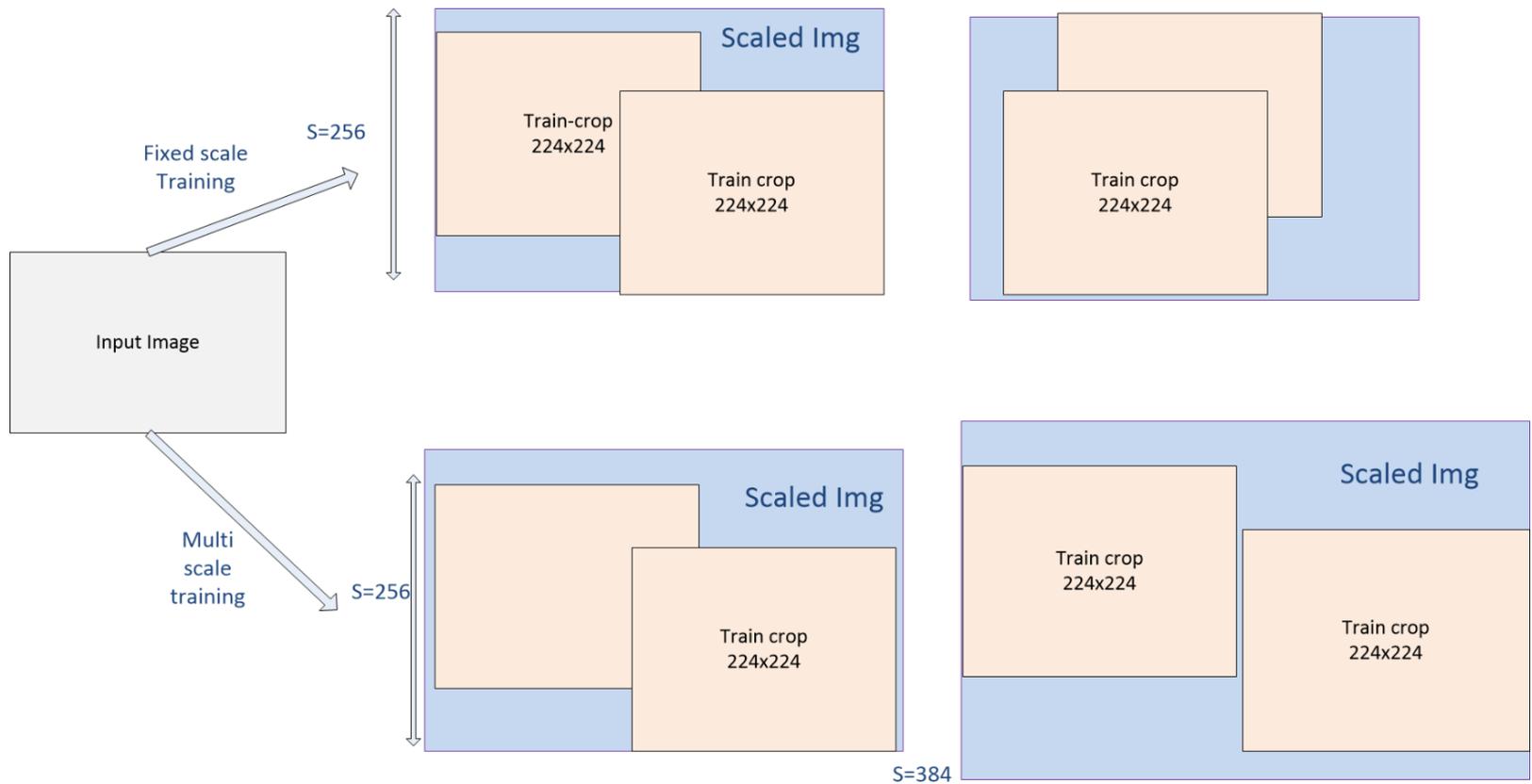


c. Crop+Flip augmentation (= 10 images)



Data augmentation

- For both training and testing

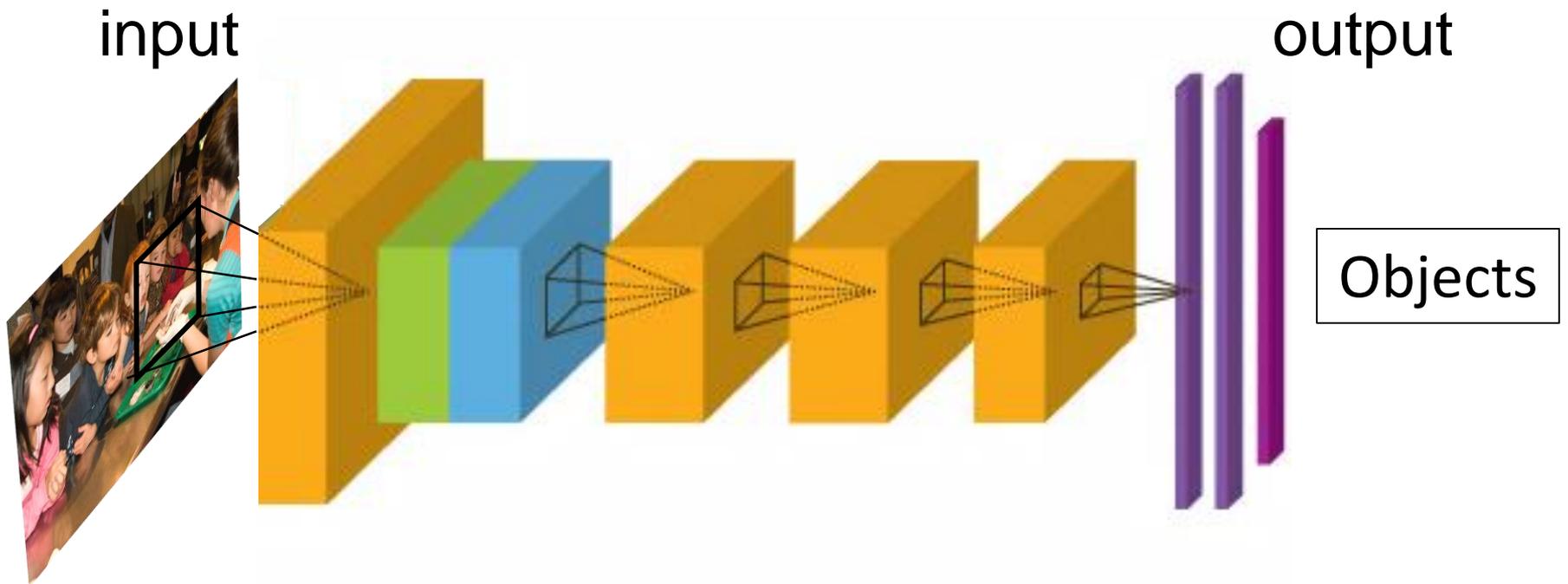


Classification results on ImageNet 2012

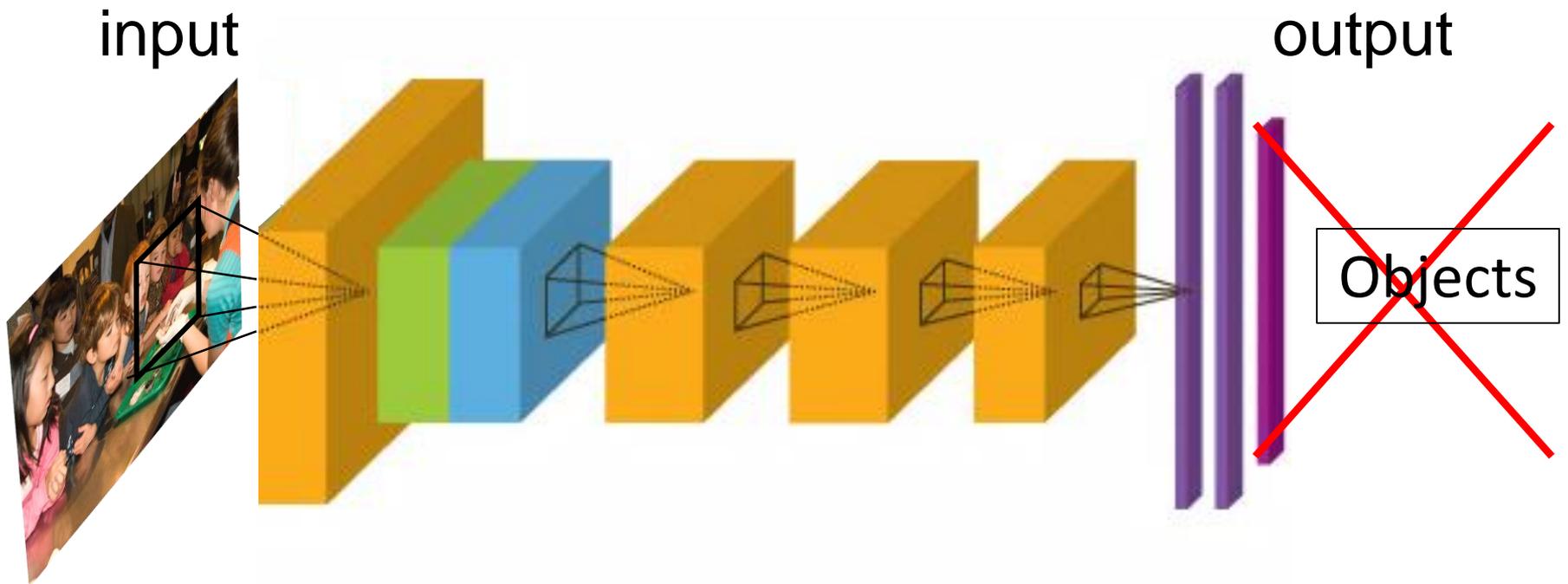
Number of Models	Number of Crops	Computational Cost	Top-5 Error	Compared to Base
1	1 (center crop)	1x	10.07%	-
1	10*	10x	9.15%	-0.92%
1	144 (Our approach)	144x	7.89%	-2.18%
7	1 (center crop)	7x	8.09%	-1.98%
7	10*	70x	7.62%	-2.45%
7	144 (Our approach)	1008x	6.67%	-3.41%

*Cropping by [Krizhevsky et al 2014]

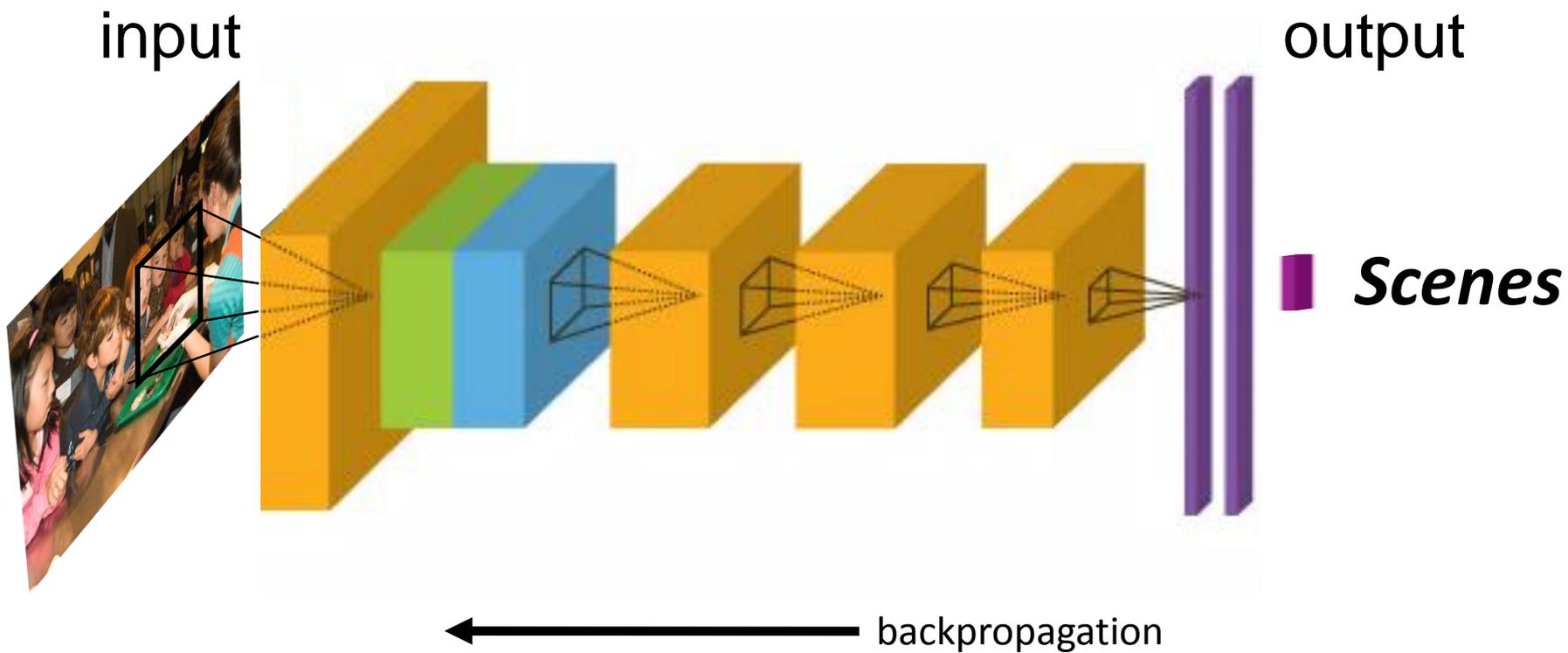
Fine-tuning



Fine-tuning



Fine-tuning



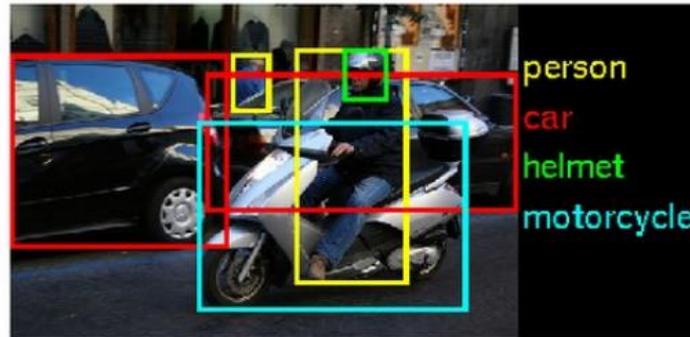
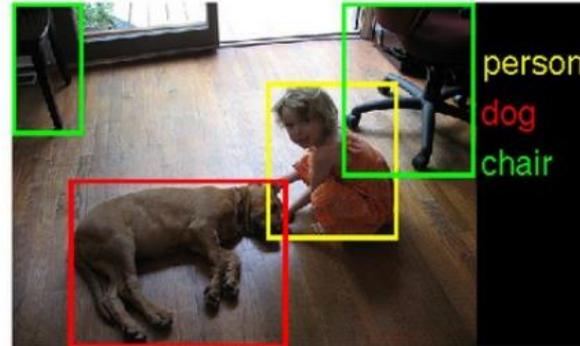
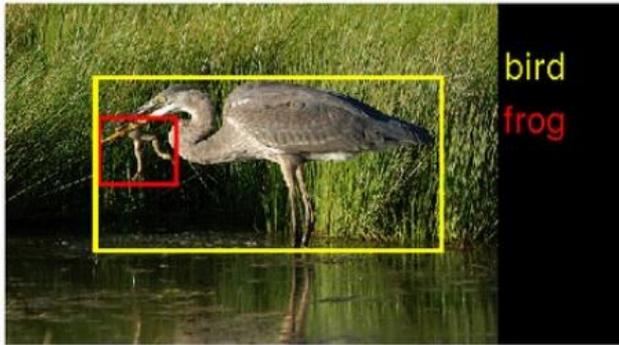
Visual Classification

Results of MIT 67 Scene Classification

Method	mean Accuracy
ROI + Gist[36]	26.1
DPM[30]	30.4
Object Bank[24]	37.6
RBow[31]	37.9
BoP[21]	46.1
miSVM[25]	46.4
D-Parts[40]	51.4
IFV[21]	60.8
MLrep[9]	64.0
CNN-SVM	58.4
CNNaug-SVM	69.0
CNN(AlexConvNet)+multiscale pooling [16]	68.9

Using a CNN off-the-shelf representation with linear SVMs training significantly outperforms a majority of the baselines.

Detection



Model must output:

A set of detections

Each detection has:

- confidence
 - class (integer)
 - x_1, y_1, x_2, y_2
- bounding box
coordinates

R-CNN

Rich feature hierarchies for accurate object detection and semantic segmentation
[Ross Girshick, Jeff Donahue, Trevor Darrell, Jitendra Malik]



Idea: Turn a Detection Problem into an Image Classification problem (but over image regions).



Content of every labeled bounding box for is a positive example for a class.

Every other bounding box in the image is a special **negative class**.

R-CNN

Rich feature hierarchies for accurate object detection and semantic segmentation
[Ross Girshick, Jeff Donahue, Trevor Darrell, Jitendra Malik]

Idea: Turn a Detection Problem into an Image Classification problem (but over image regions).



R-CNN: Regions with CNN features

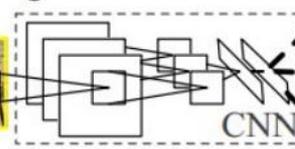


1. Input image



2. Extract region proposals (~2k)

warped region



3. Compute CNN features

aeroplane? no.

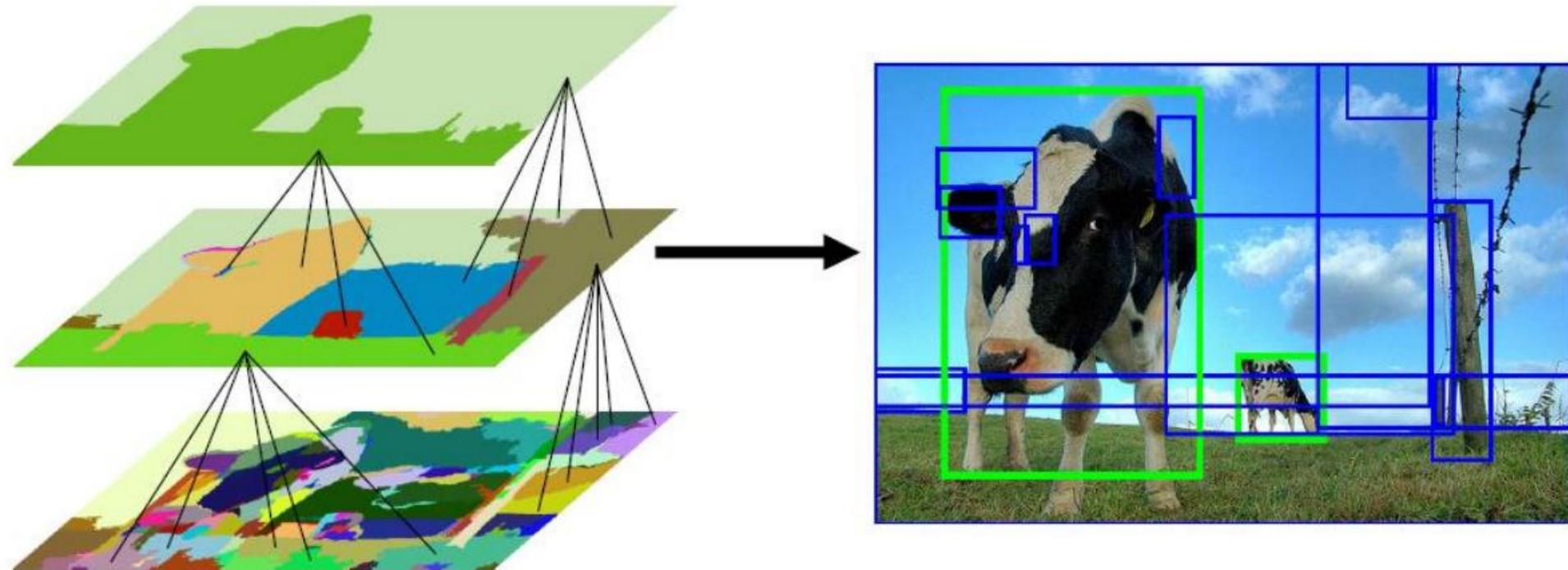
person? yes.

tvmonitor? no.

4. Classify regions

Selective Search for Object Recognition

[J. R. R. Uijlings, K. E. A. van de Sande, T. Gevers, A. W. M. Smeulders]

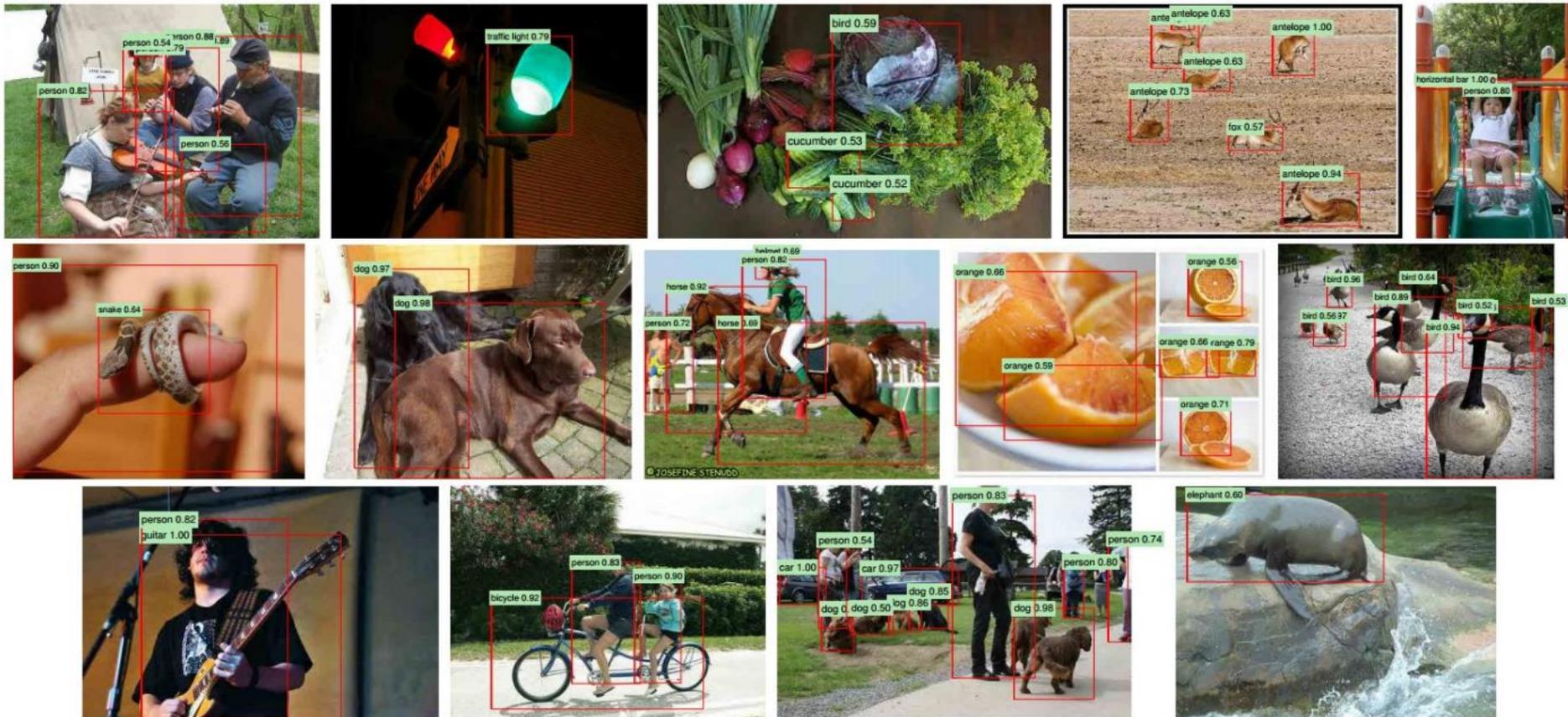


Gives on average ~2,000 candidate region proposals per image.
(This paradigm currently outperform the “sliding window” approach)

R-CNN Results

Rich feature hierarchies for accurate object detection and semantic segmentation

[Ross Girshick, Jeff Donahue, Trevor Darrell, Jitendra Malik]

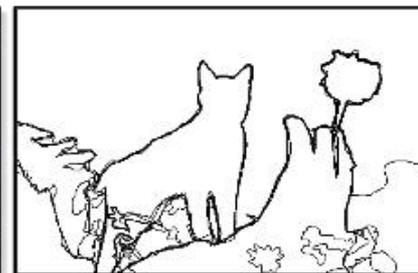
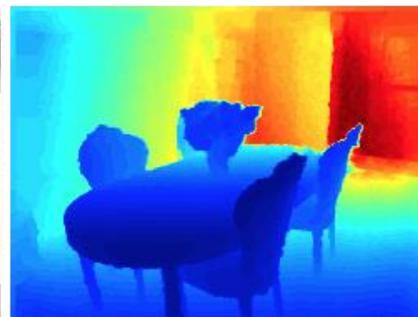


Pixels in, pixels out

semantic
segmentation

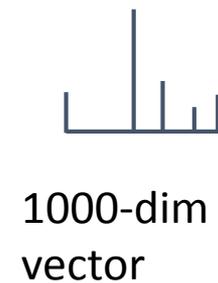
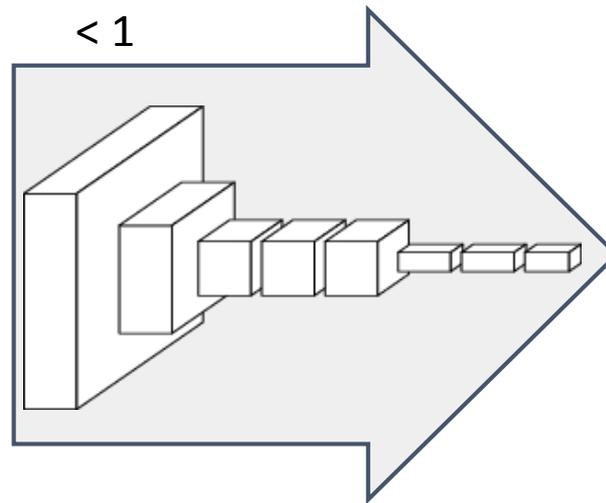


monocular depth estimation (Liu et al. 2015)



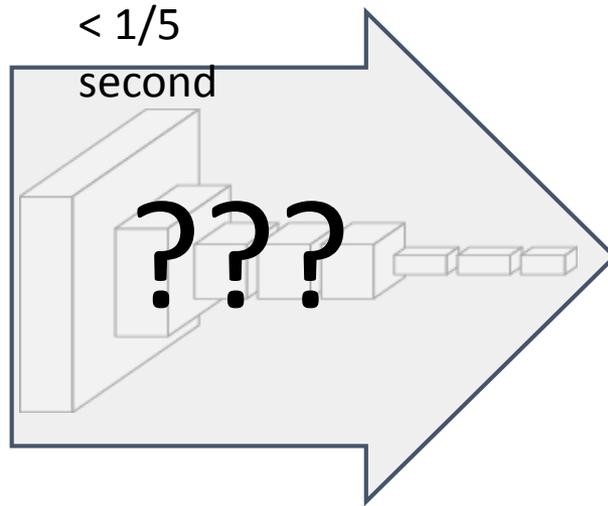
boundary prediction (Xie & Tu 2015)

ConvNets perform Classification



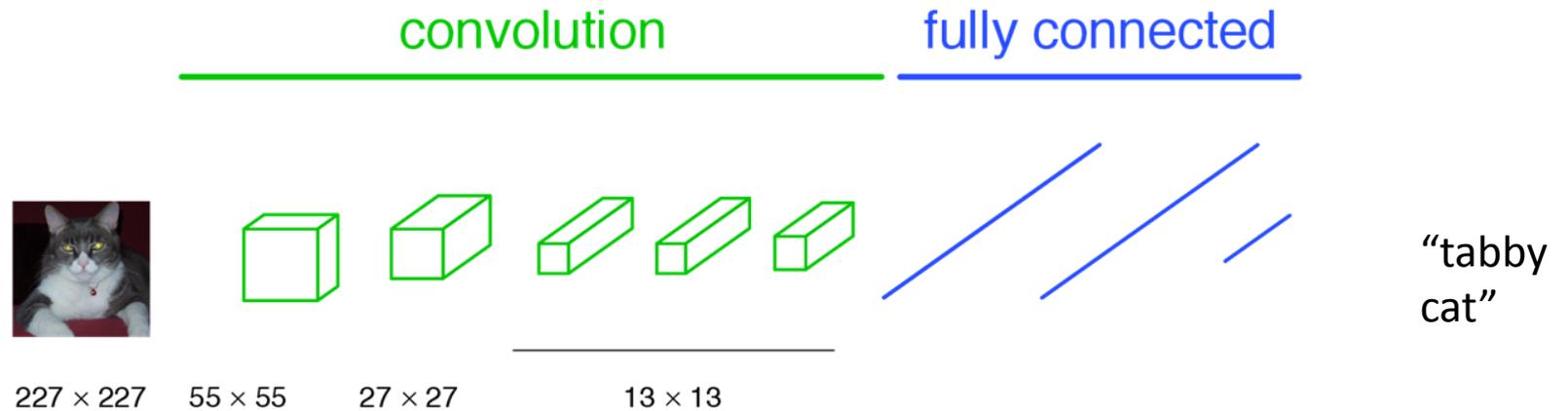
“tabby
cat”

end-to-end learning

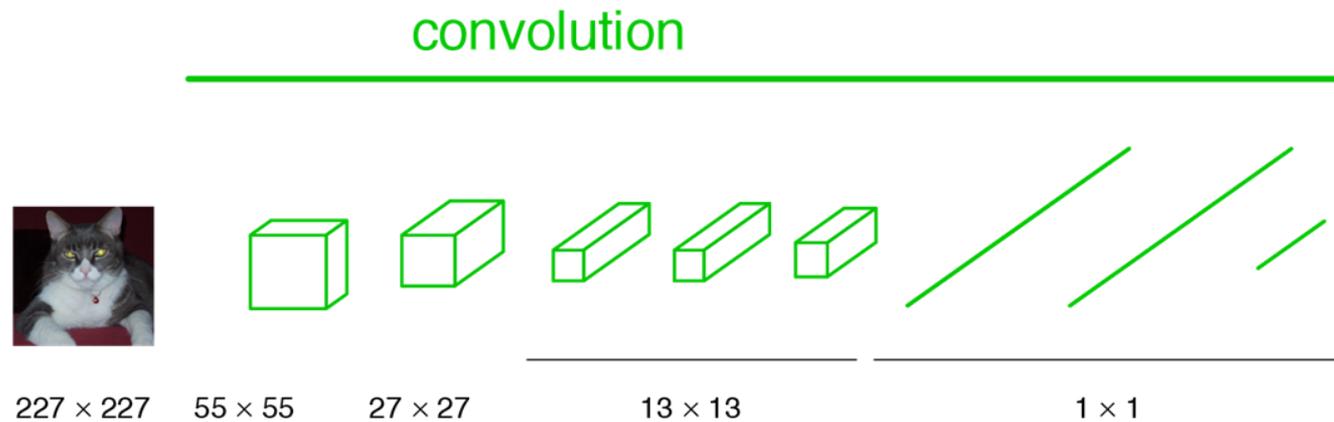


end-to-end learning

A Classification Network



Becoming fully convolutional



Becoming fully convolutional



$H \times W$

convolution



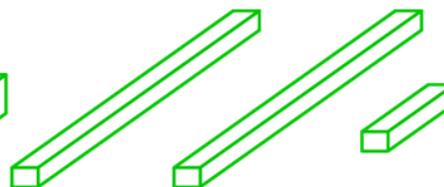
$H/4 \times W/4$



$H/8 \times W/8$

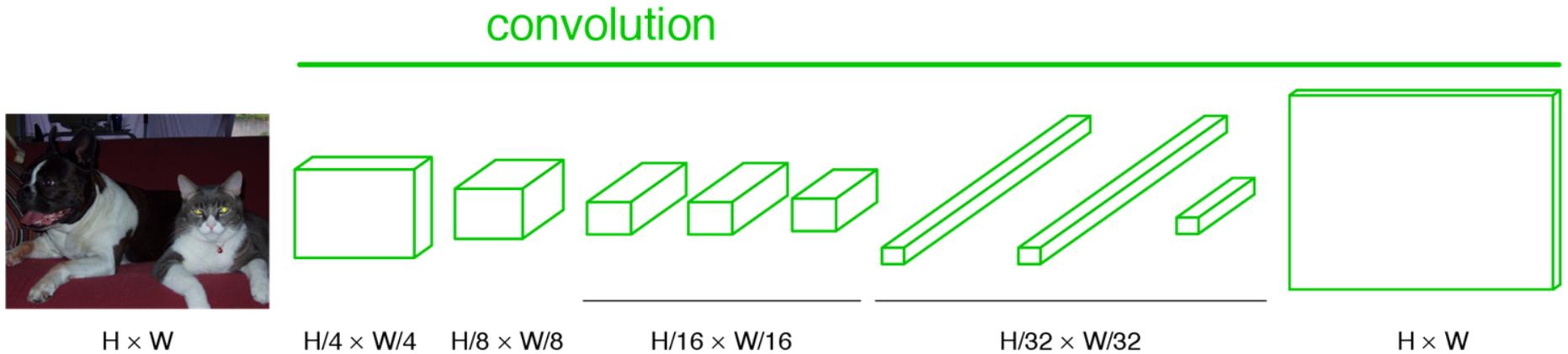


$H/16 \times W/16$

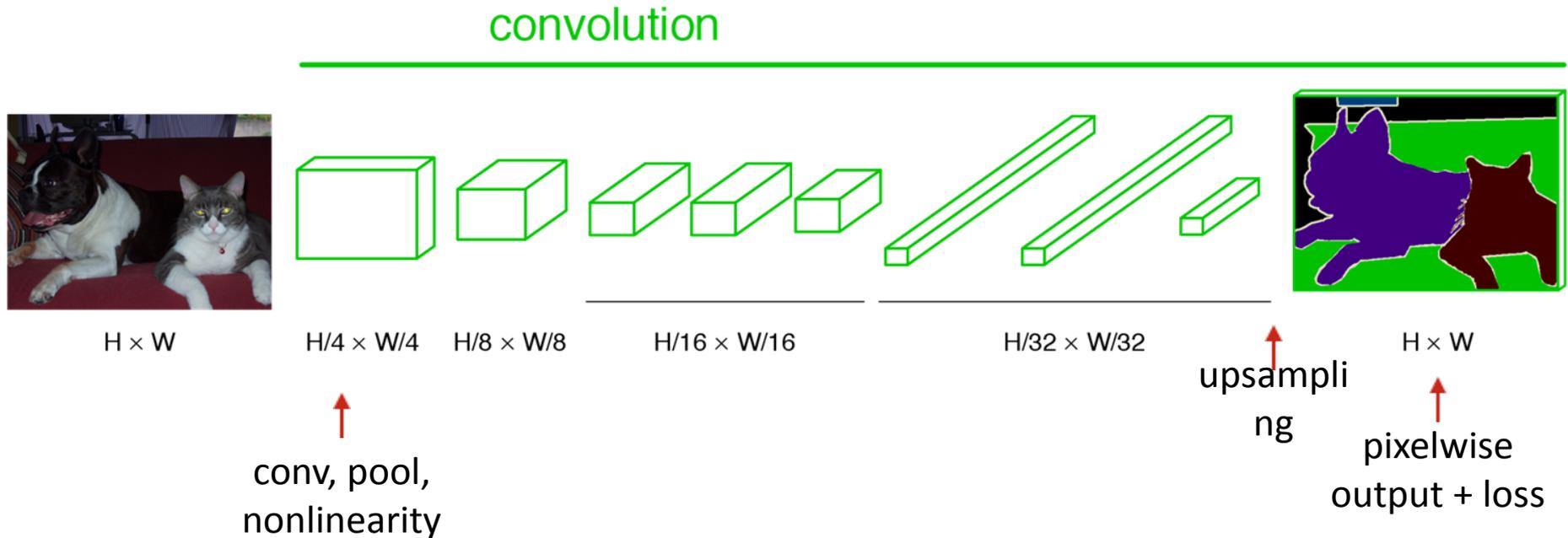


$H/32 \times W/32$

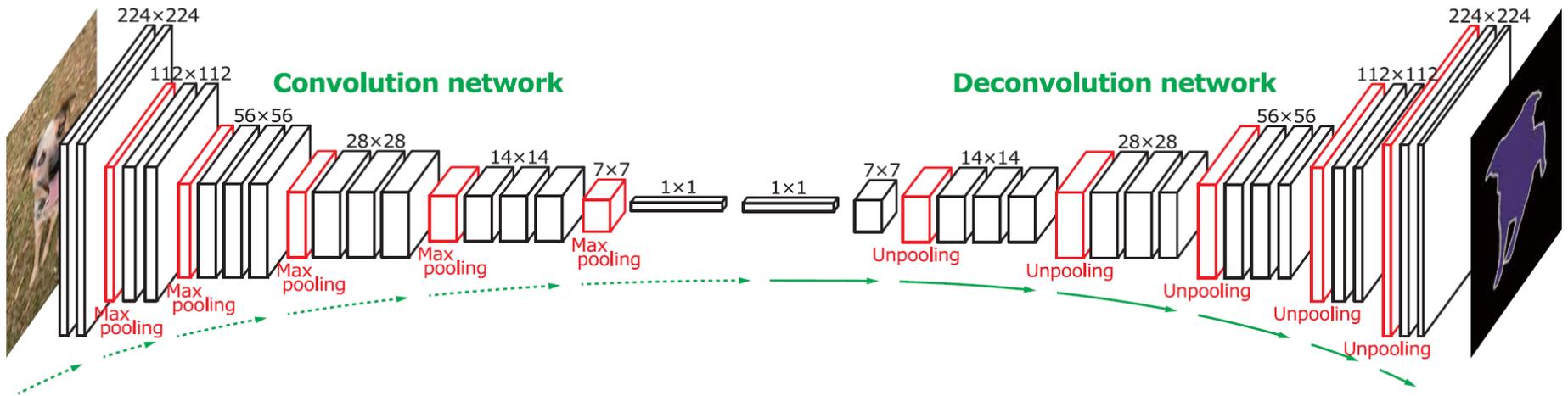
Upsampling output



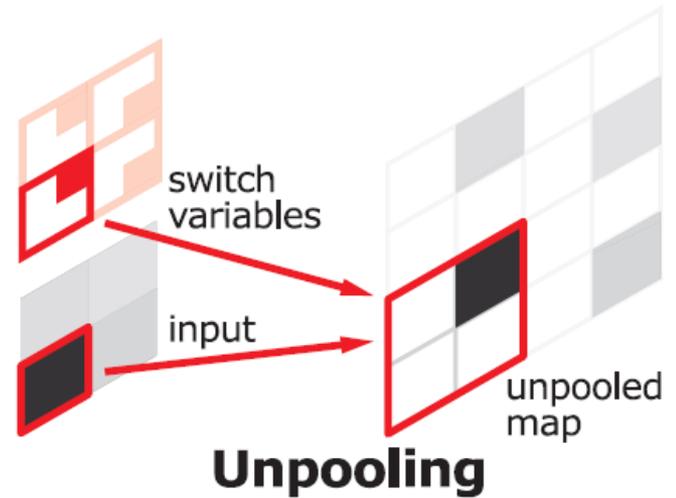
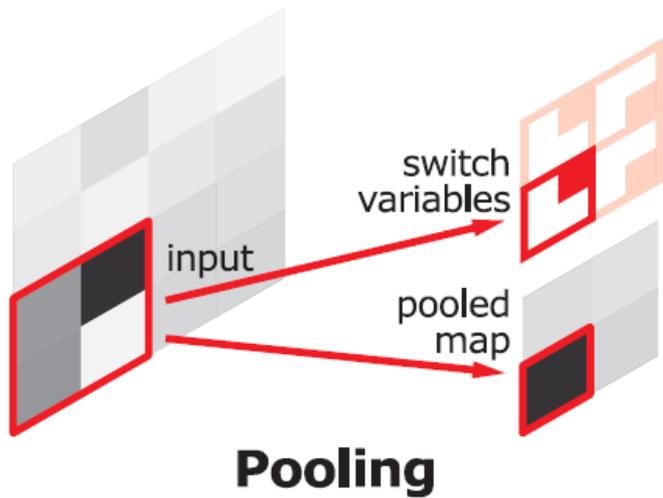
End-to-end, Pixels-to-pixels network



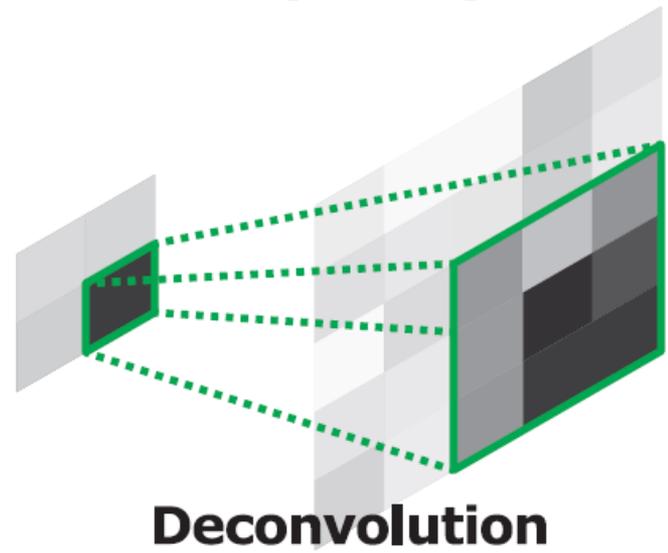
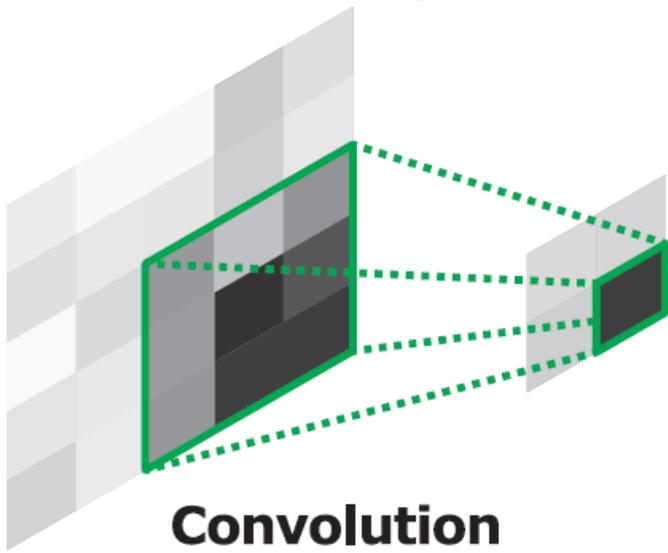
Deconvolutional network



Upsampling



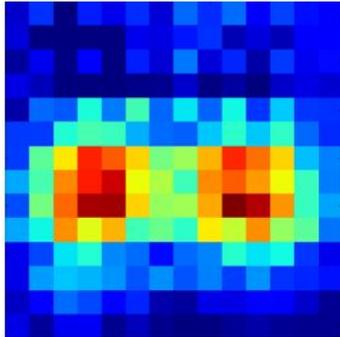
Deconvolution



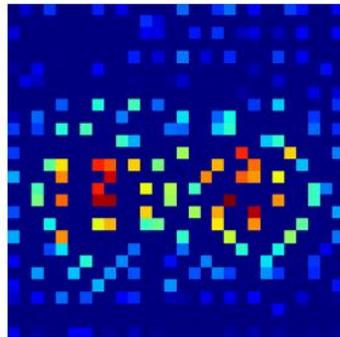
Unpooling and Deconv Effects



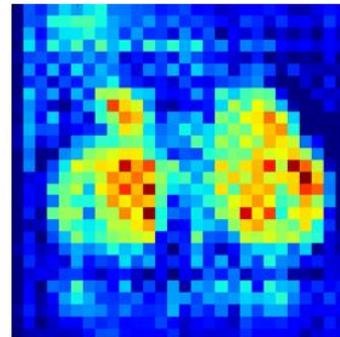
(a)



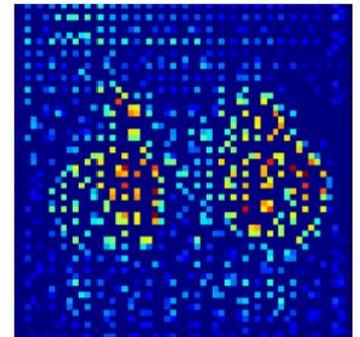
(b)



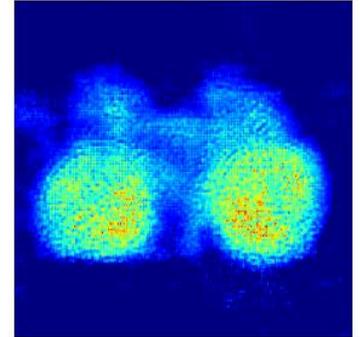
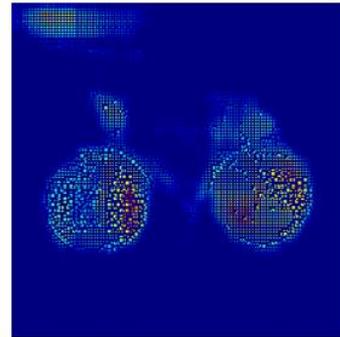
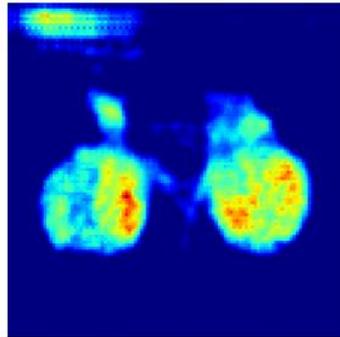
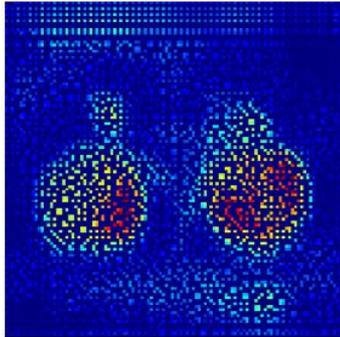
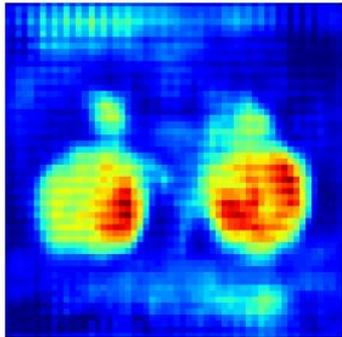
(c)



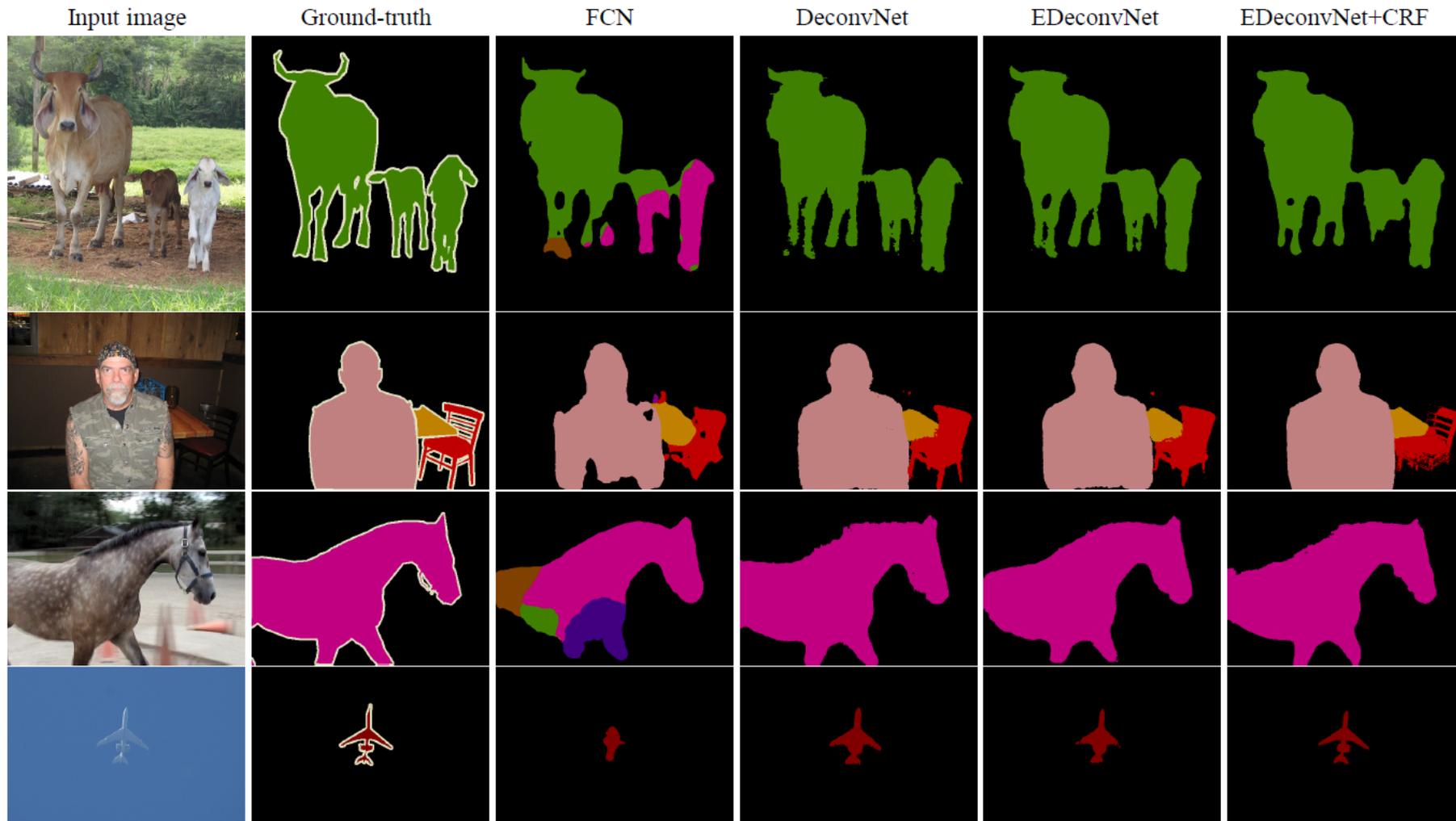
(d)



(e)



Results - segmentation



(a) Examples that our method produces better results than FCN [17].

Predicting Human Visual Memory

Memorability = The likelihood of remembering a particular image.

Welcome to the

Visual Memory Game

A stream of images will be presented on the screen for 1 second each.

Your task:

Clap anytime you see an image you saw before in this experiment.

Ready?



(Seriously, get ready to clap. The images go by fast...)









<clap!>













<clap!>

Measuring Memorability

Vigilance repeat

Memorability is an intrinsic property of an image!

Memorability = Probability of correctly detecting a repeat after a single view of an image in a long sequence.

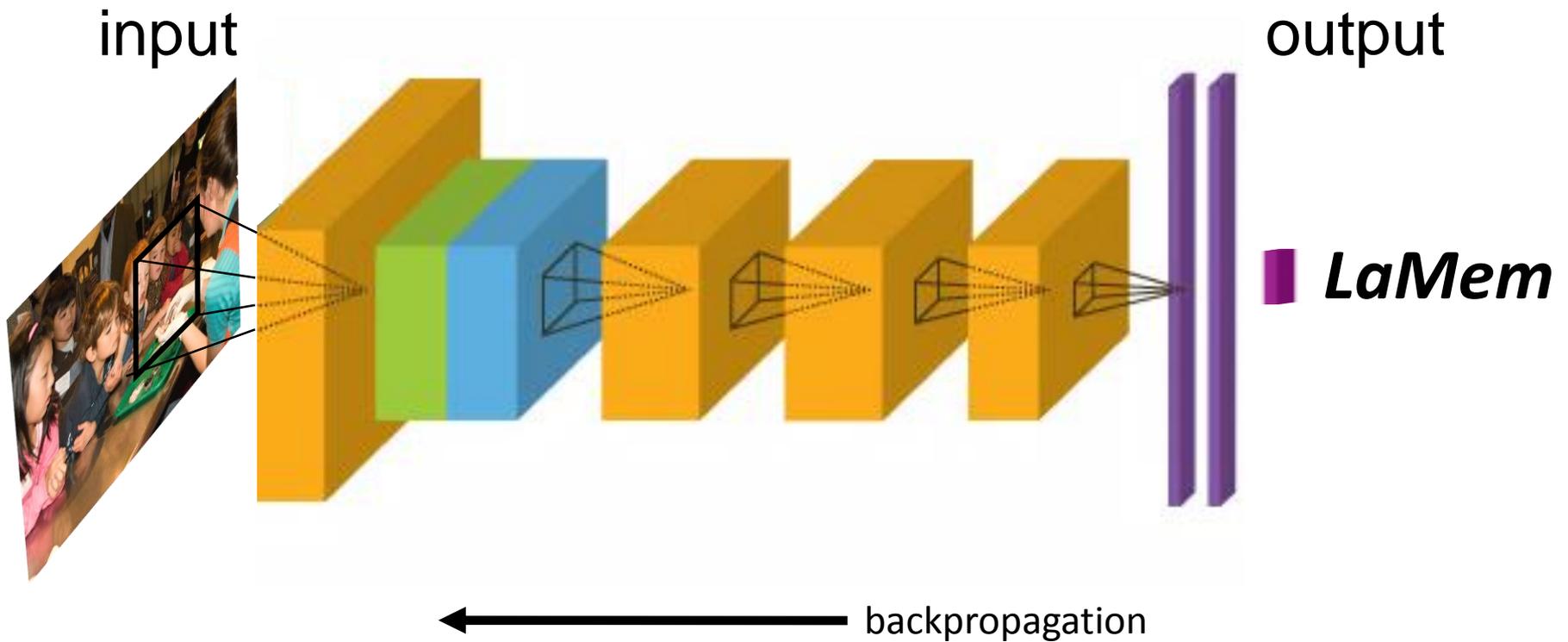
La Mem

- No single focus
- Distant view
- Static
- Common

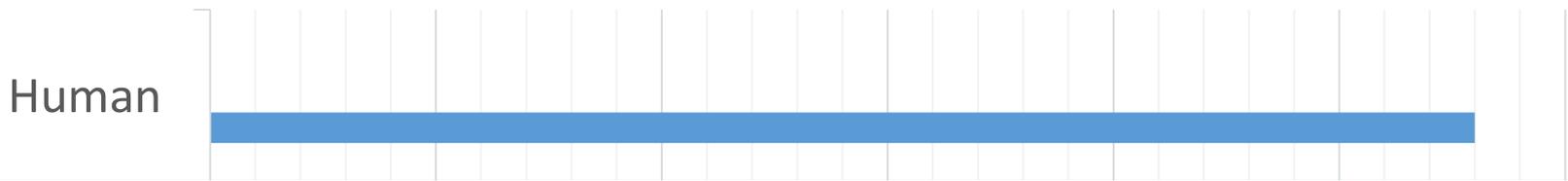
- Focused
- Enclosed Setting
- Dynamics
- Unusual

memorability

Training MemNet

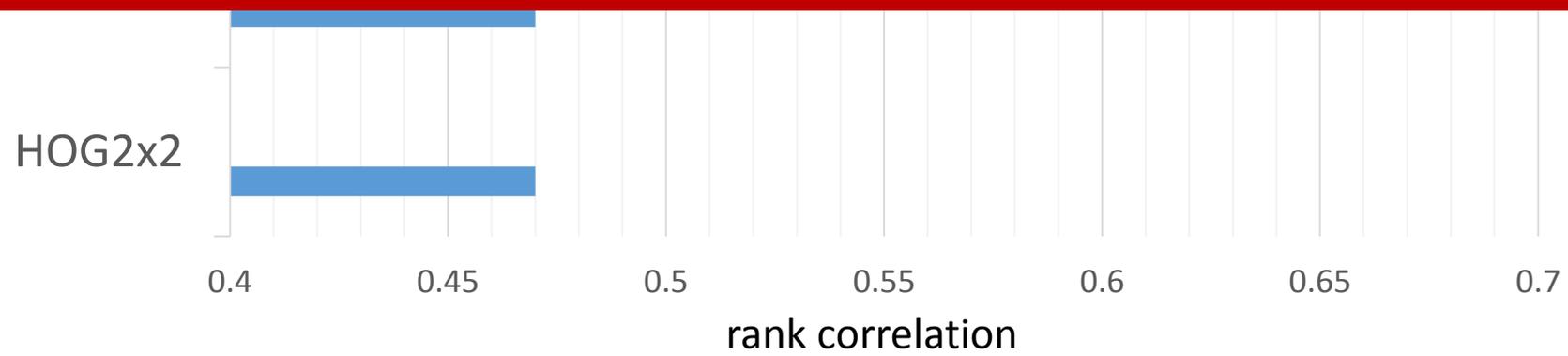


MemNet Performance



Human rank correlation: 0.68

Prediction rank correlation: 0.64!



Visualizing Neurons

positive



<http://memorability.csail.mit.edu>

strong negative



Predicting popularity

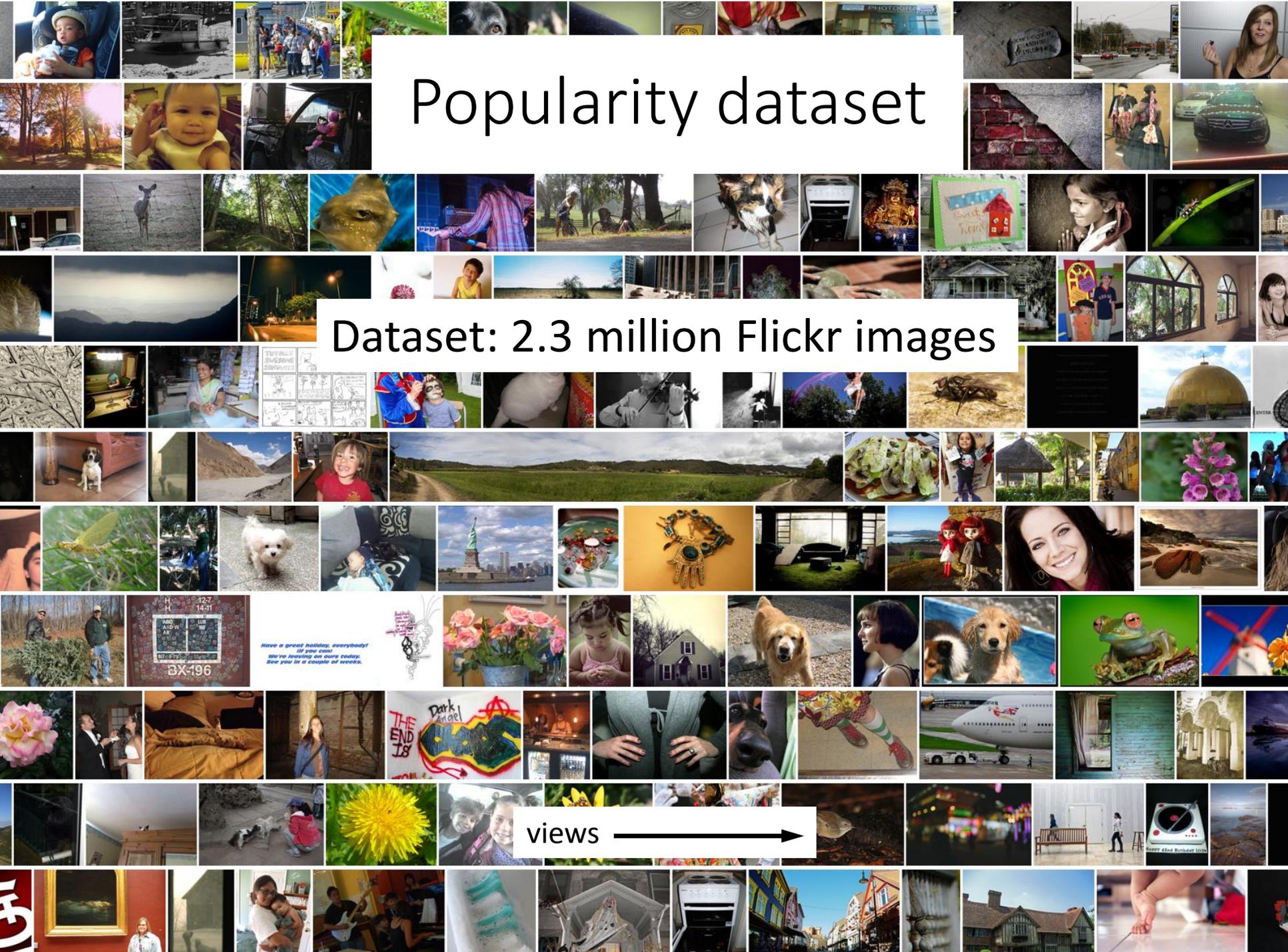


‘selfie selection’

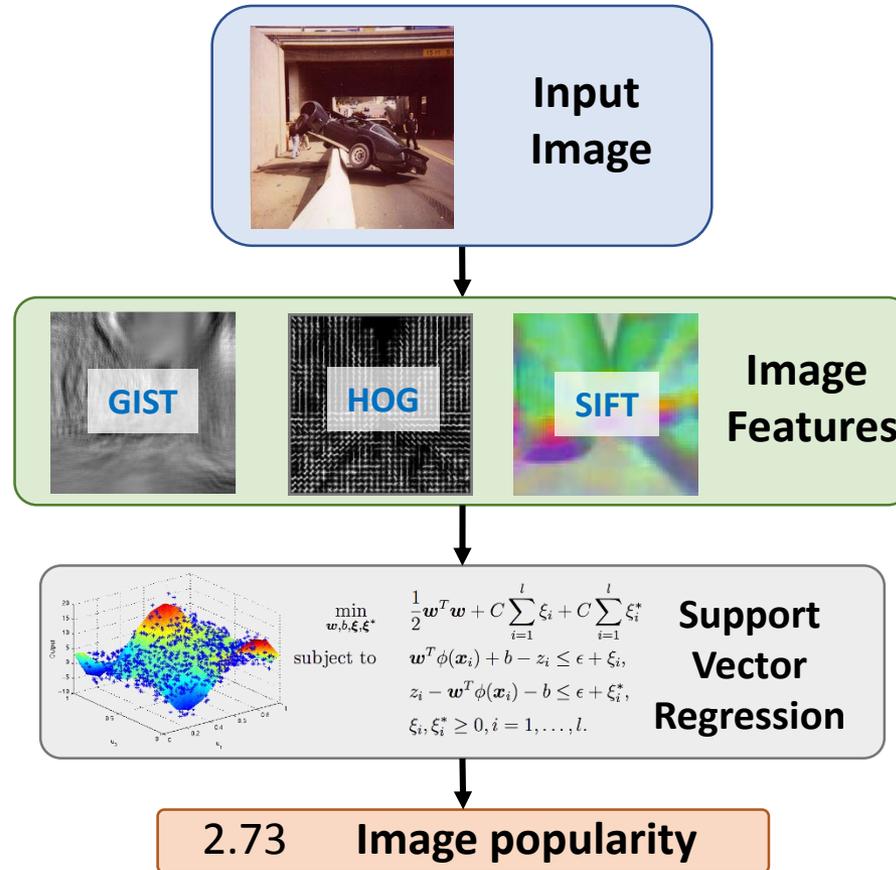
Popularity dataset

Dataset: 2.3 million Flickr images

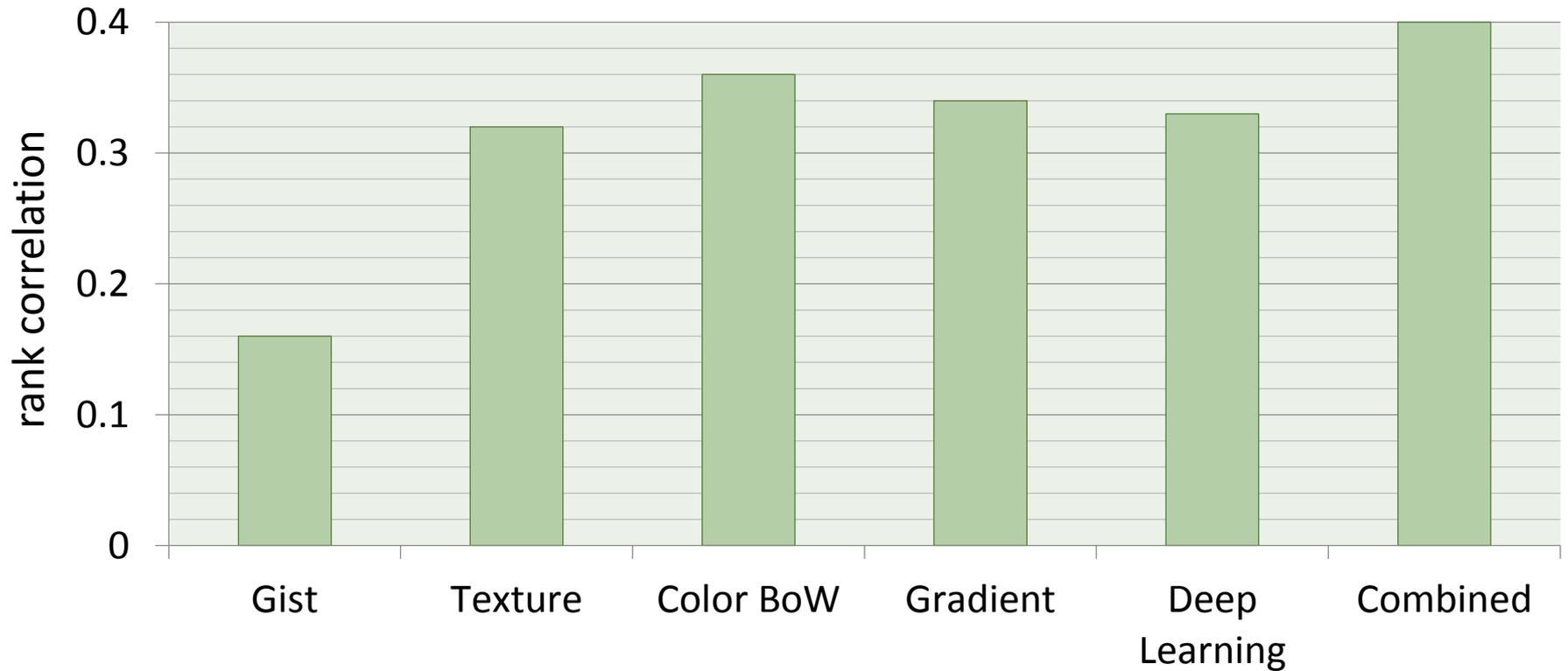
views 



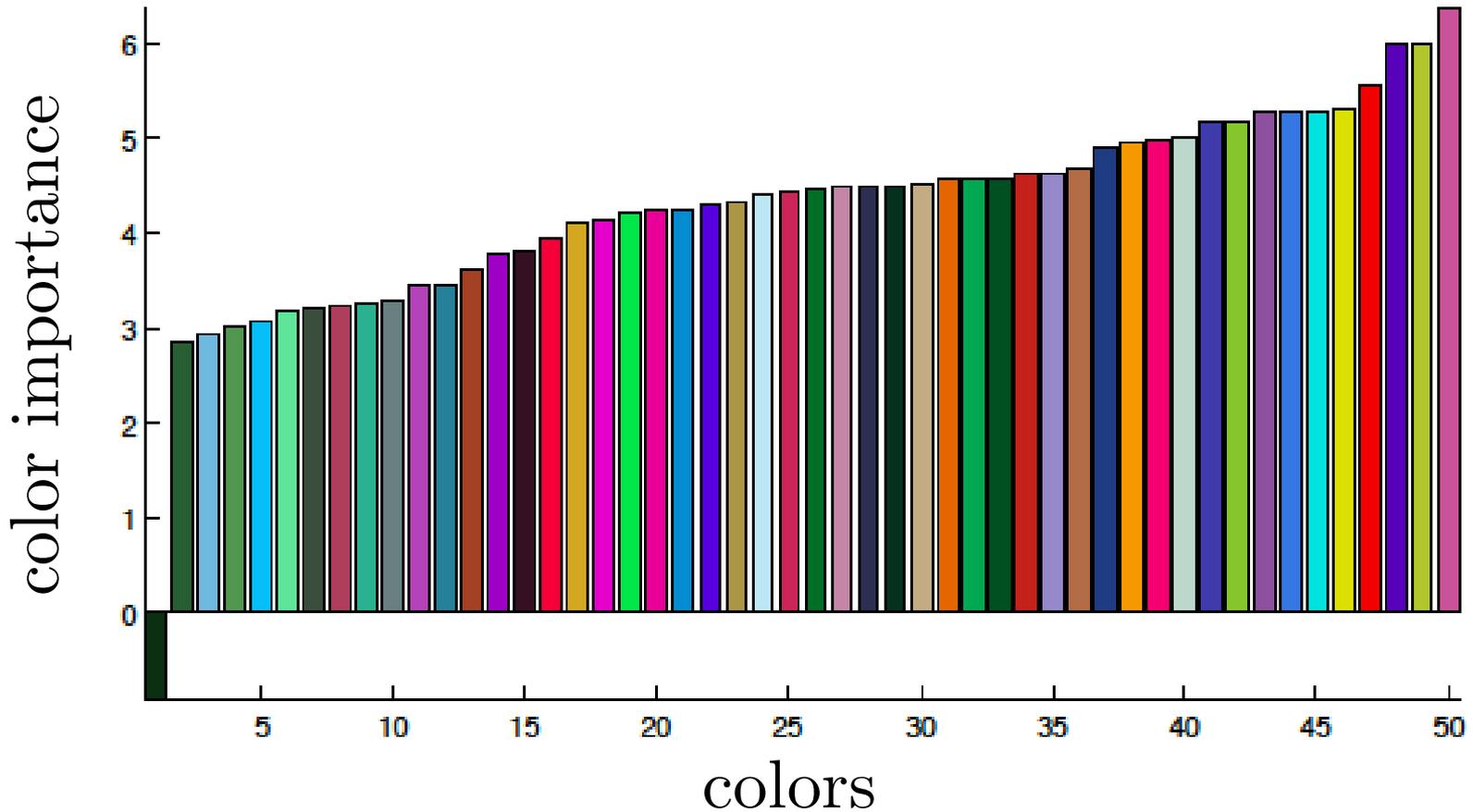
Predicting popularity



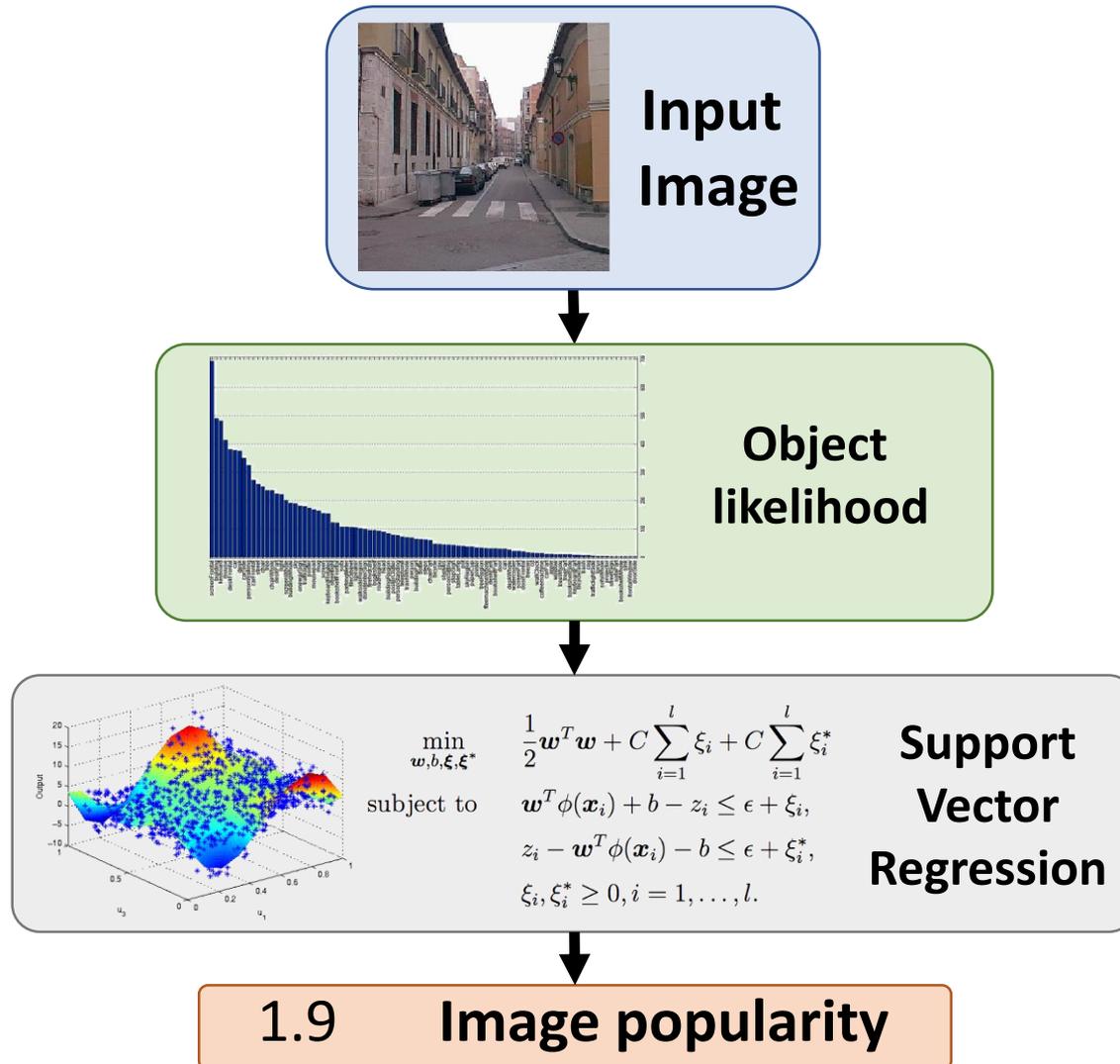
Predicting popularity



What makes an image popular?



What makes an image popular?



What makes an image popular?

Medium positive impact

giant panda



ladybug



basketball



plow



cheetah



llama



What makes an image popular?

Strong positive impact



brassiere



revolver



miniskirt



maillot



bikini



cup

What makes an image popular?

Negative impact



spatula



plunger



laptop

http://popularity.csail.mit.edu

Popularity Demo

How likely is your image to become popular? Upload it to find out!

Upload: No file chosen

or

URL:

or

Click One:



Popularity API

Usage: `http://popularity.csail.mit.edu/cgi-bin/image.py?url=IMG_URL`

Example:

<http://popularity.csail.mit.edu/cgi-bin/image.py?url=http://popularity.csail.mit.edu/demo/1.jpg>

Notice: Please do not overload our server by querying repeatedly in a short period of time. This is a free service for academic research and education purposes only. It has no guarantee of any kind. For any questions or comments regarding this API or potential commercial applications, please contact [Aditya Khosla](#).

Media coverage



http://popularity.csail.mit.edu

Popularity Demo

How likely is your image to become popular? Upload it to

Popularity API

Usage: <http://popularity.csail.mit.edu/cgi->

To: khosla@csail.mit.edu
popularity

Dear Aditya Khosla,

This popularity calculator is a nice initiative, but i think these girls deserve much better scores than 5.

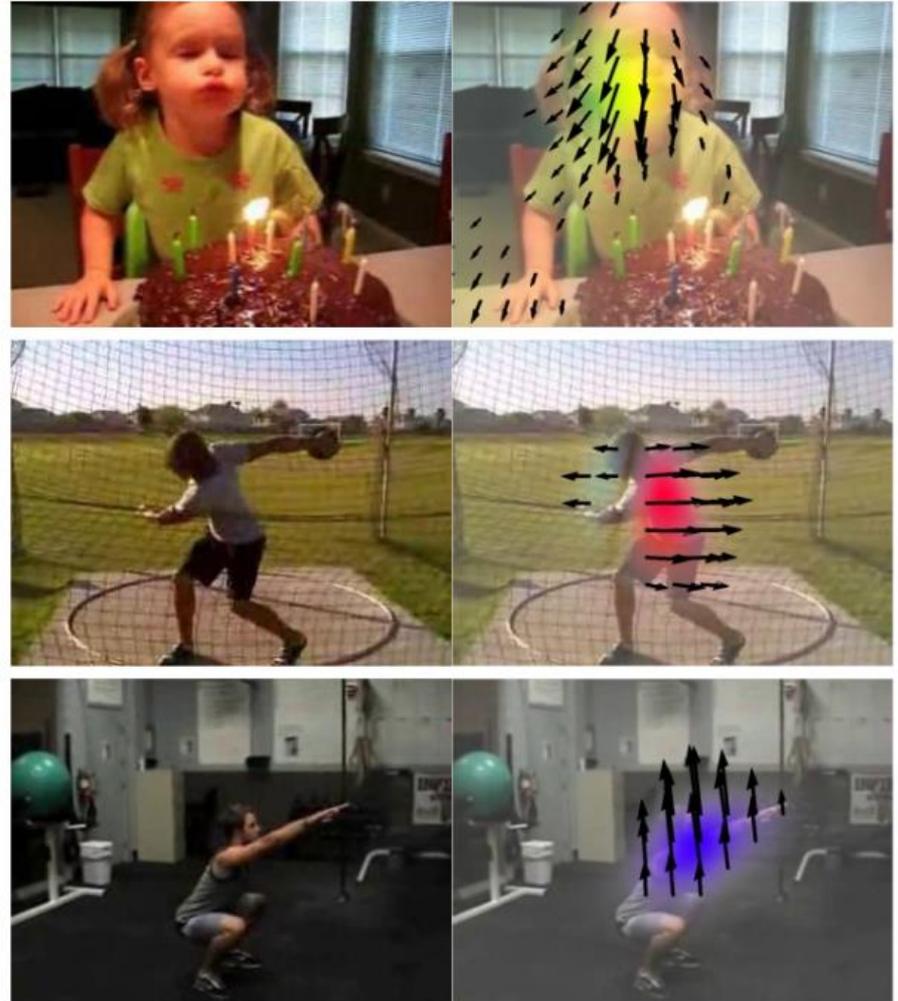
Best regards,



Predicting the future

Goal:

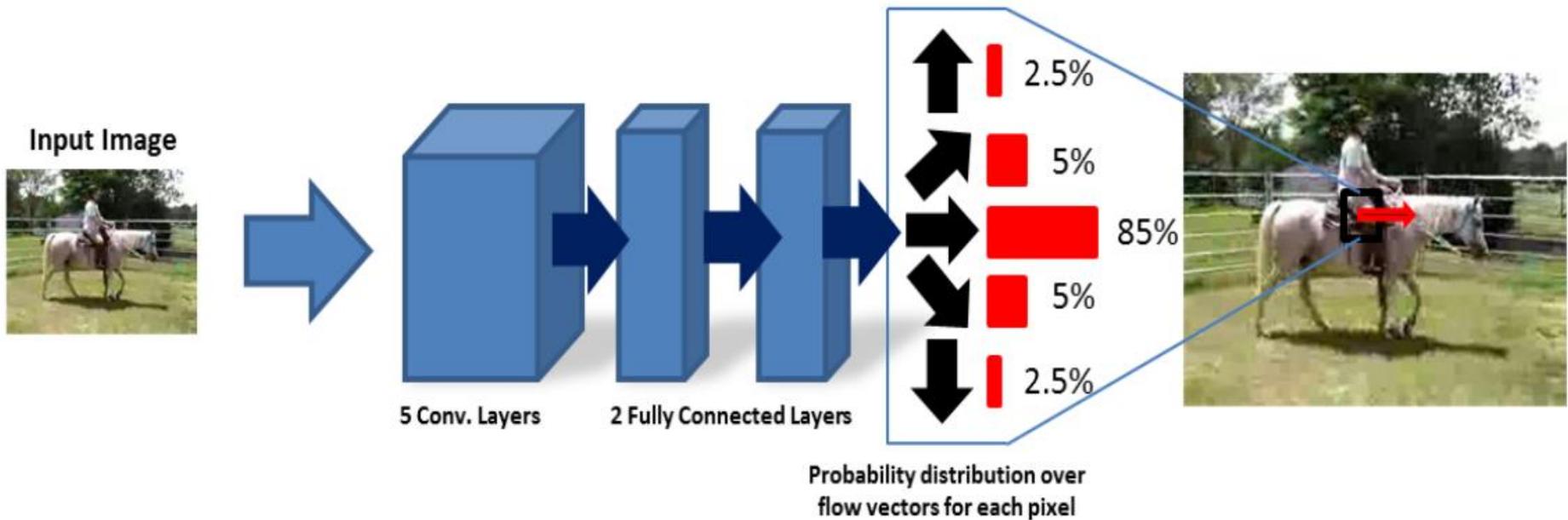
- predict Lucas-Kanade optical flow given just one image!



(a) Input Image

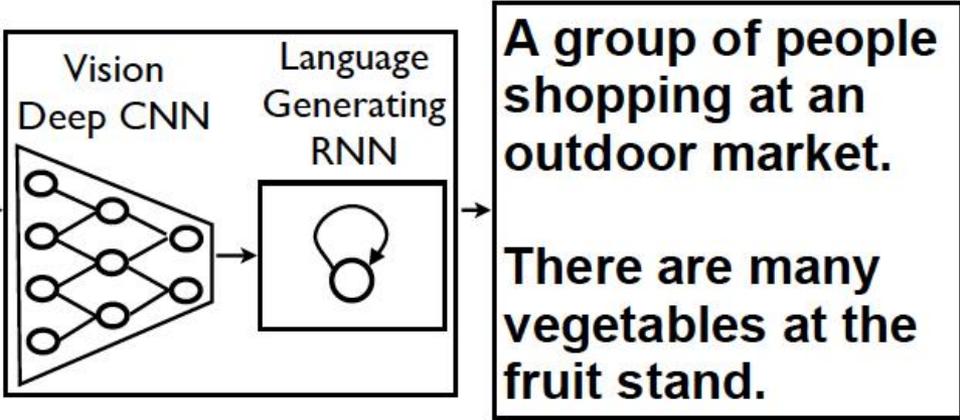
(b) Prediction

Predicting the future

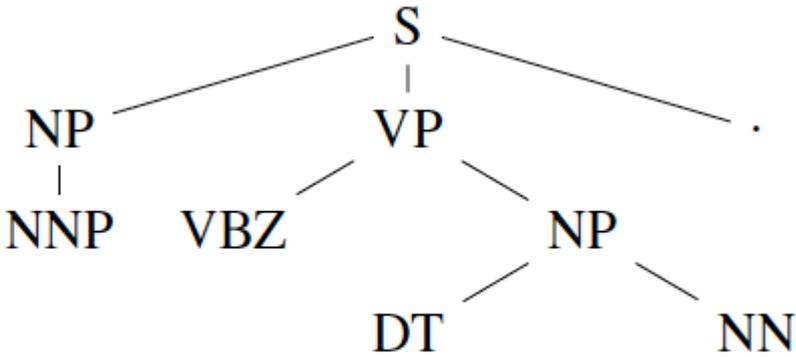


Learning sequences

Even where you might not expect a sequence...



John has a dog . →

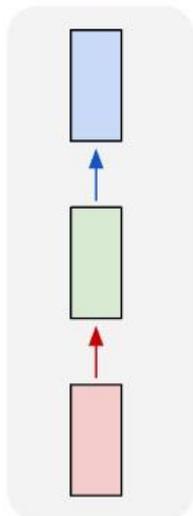


John has a dog . →

(S (NP NNP)_{NP} (VP VBZ (NP DT NN)_{NP})_{VP} .)_S

How do we model sequences?

one to one

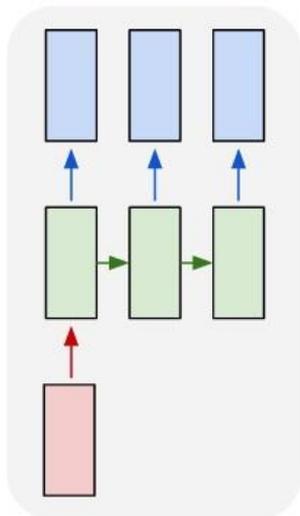


Input: No sequence

Output: No sequence

Example: "standard" classification / regression problems

one to many

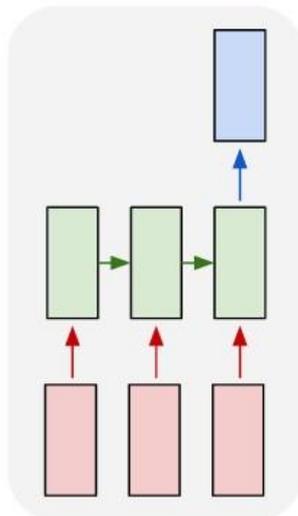


Input: No sequence

Output: Sequence

Example: Im2Caption

many to one

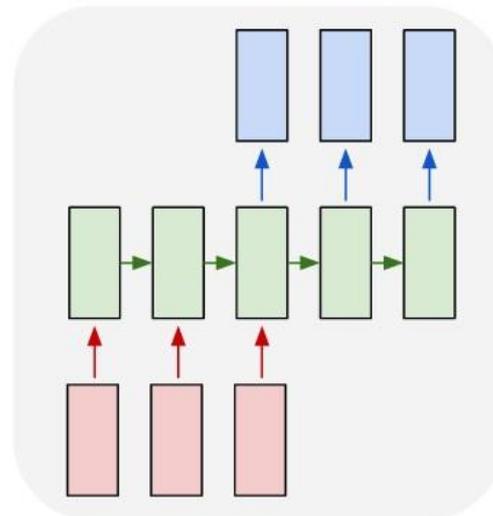


Input: Sequence

Output: No sequence

Example: sentence classification, multiple-choice question answering

many to many

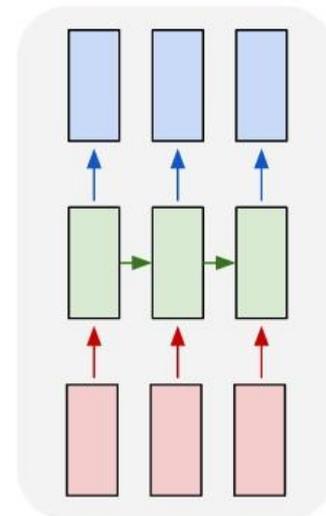


Input: Sequence

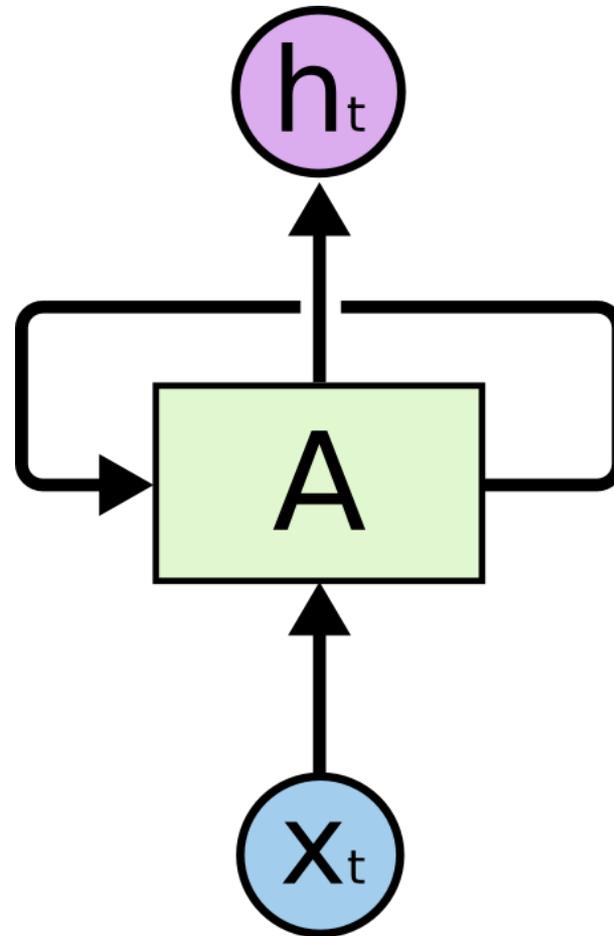
Output: Sequence

Example: machine translation, video captioning, open-ended question answering, video question answering

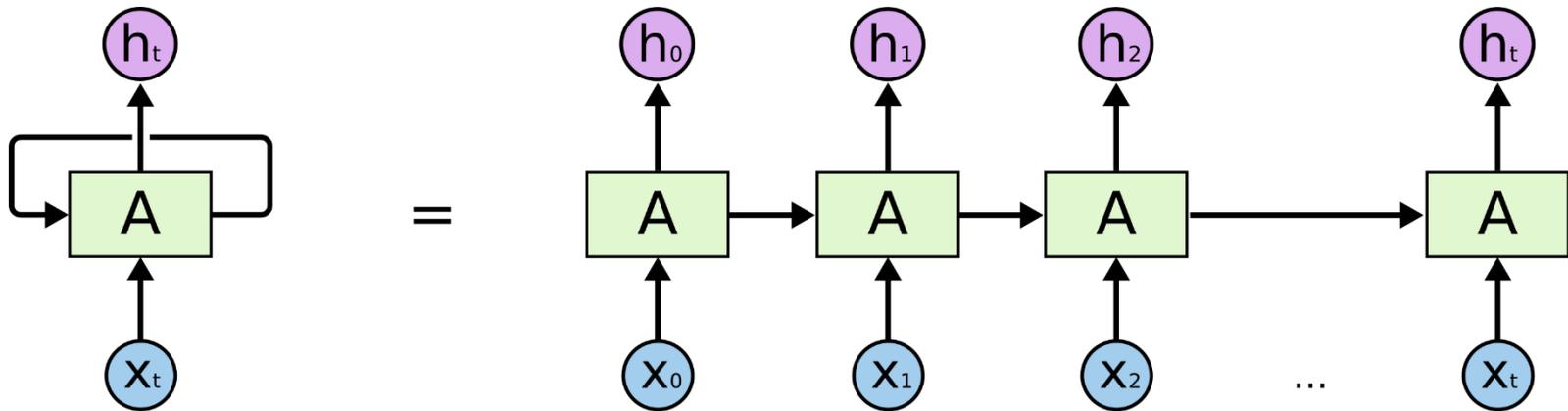
many to many



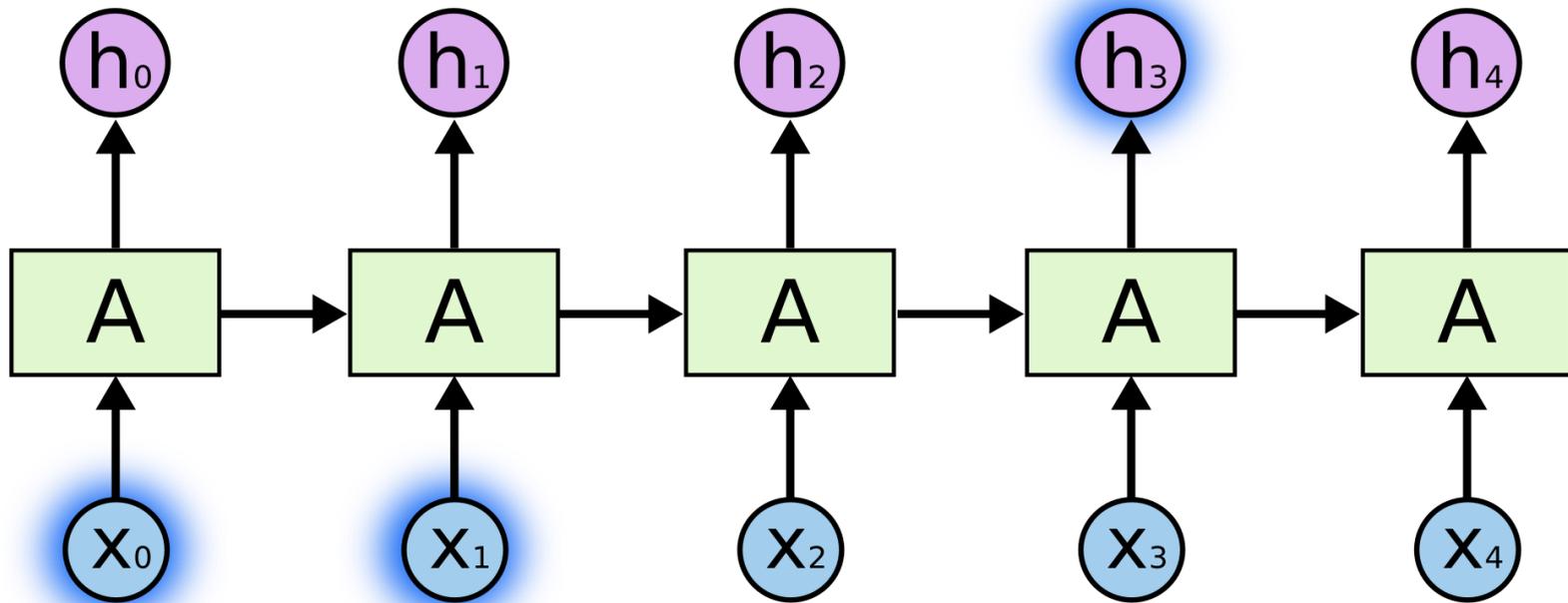
Recurrent Neural Networks (RNNs)



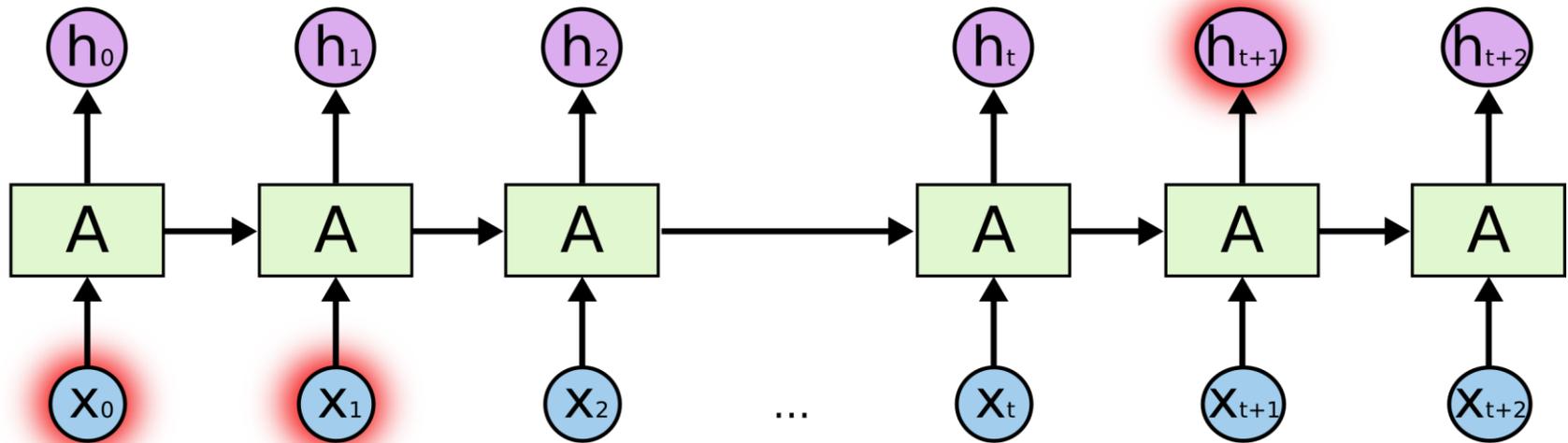
Recurrent Neural Networks (RNNs)



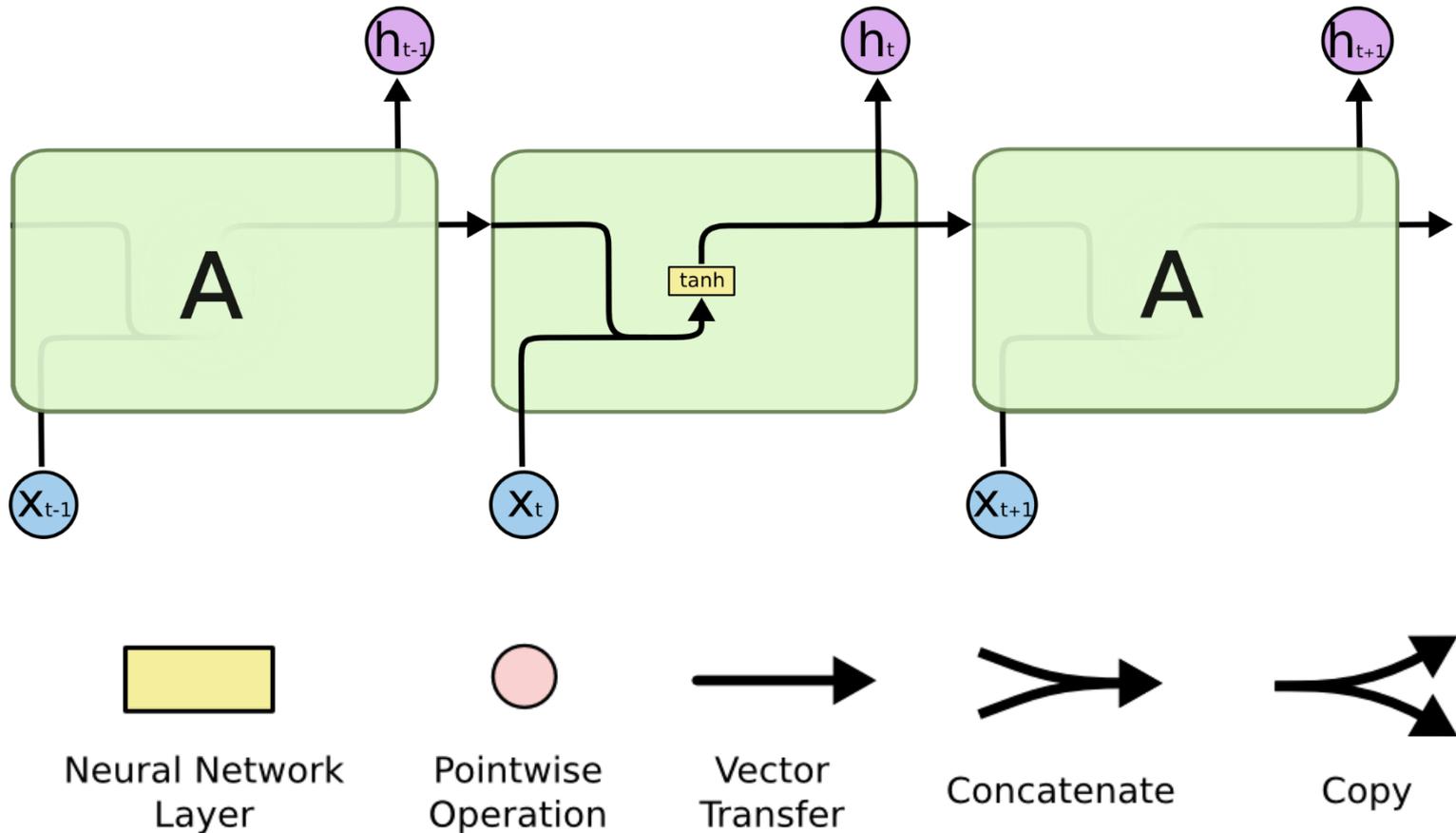
Recurrent Neural Networks (RNNs)



Long-term dependencies— hard to model!

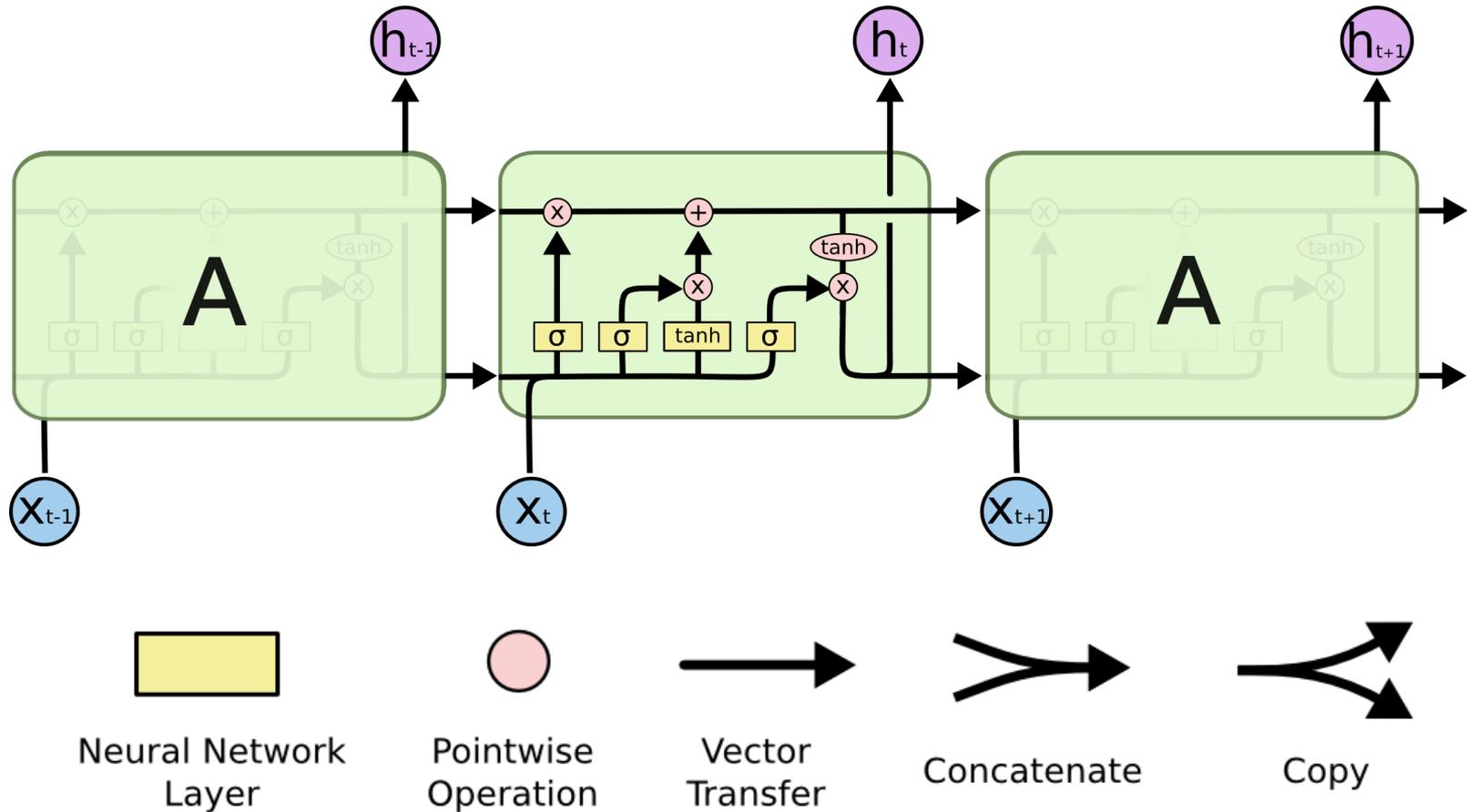


From plain RNNs to LSTMs



(LSTM: Long Short Term Memory Networks)

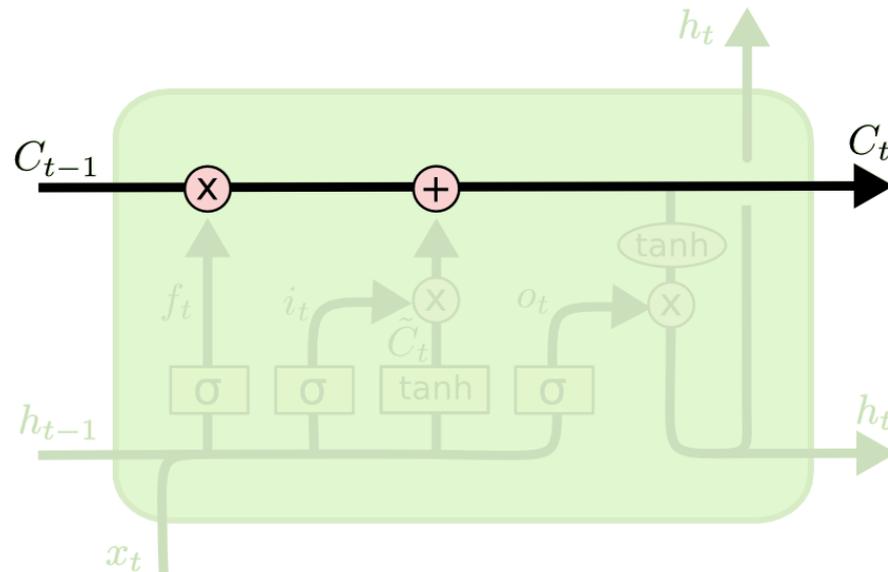
From plain RNNs to LSTMs



(LSTM: Long Short Term Memory Networks)

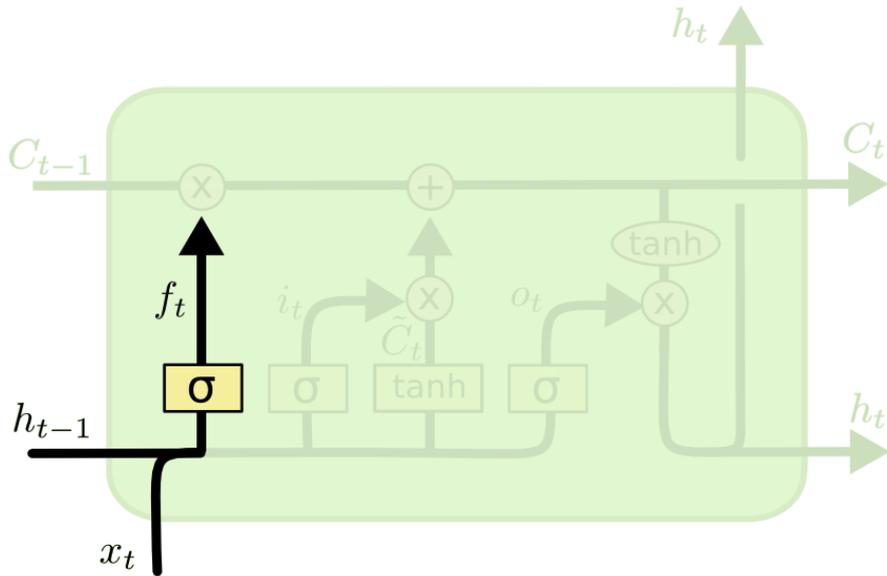
LSTMs Intuition: Memory

- Cell State / Memory



LSTMs Intuition: Forget Gate

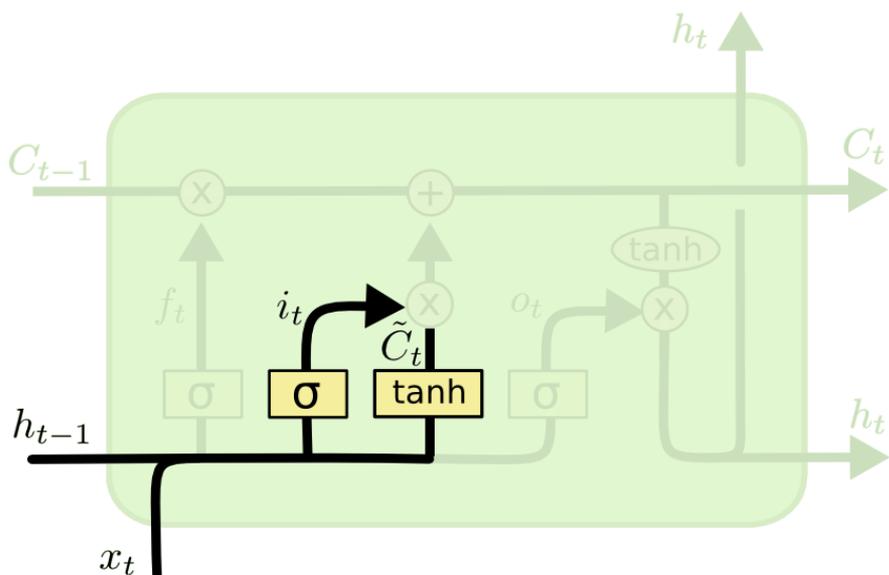
- Should we continue to remember this “bit” of information or not?



$$f_t = \sigma (W_f \cdot [h_{t-1}, x_t] + b_f)$$

LSTMs Intuition: Input Gate

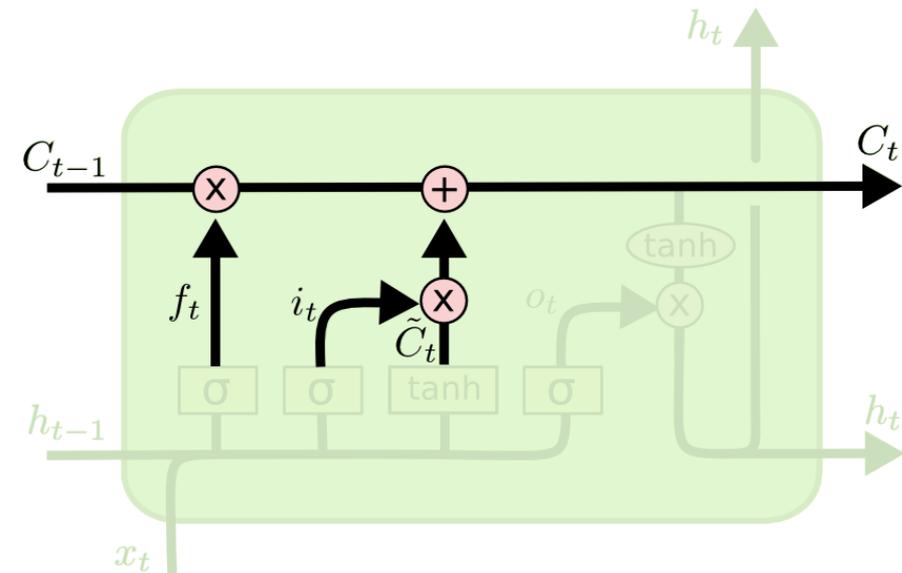
- Should we update this “bit” of information or not?
 - If so, with what?



$$i_t = \sigma(W_i \cdot [h_{t-1}, x_t] + b_i)$$
$$\tilde{C}_t = \tanh(W_C \cdot [h_{t-1}, x_t] + b_C)$$

LSTMs Intuition: Memory Update

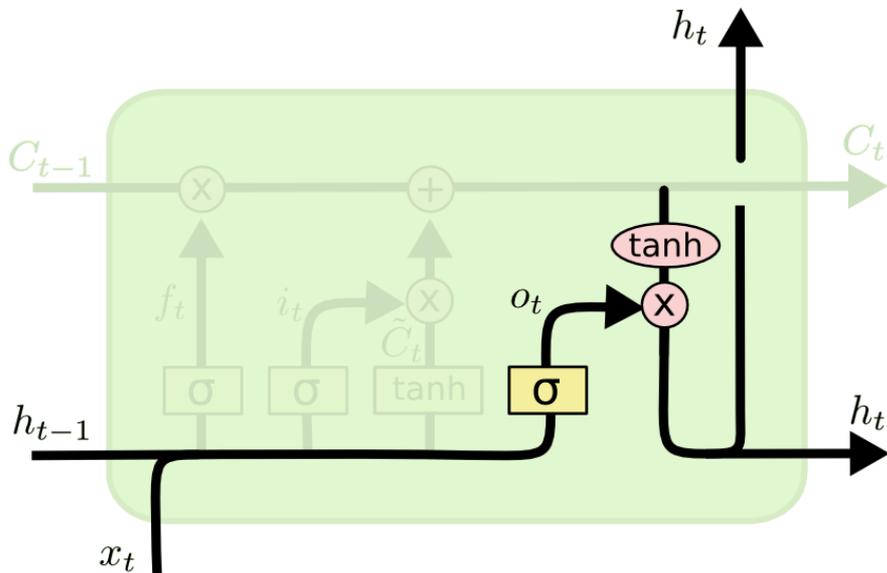
- Forget that + memorize this



$$C_t = f_t * C_{t-1} + i_t * \tilde{C}_t$$

LSTMs Intuition: Output Gate

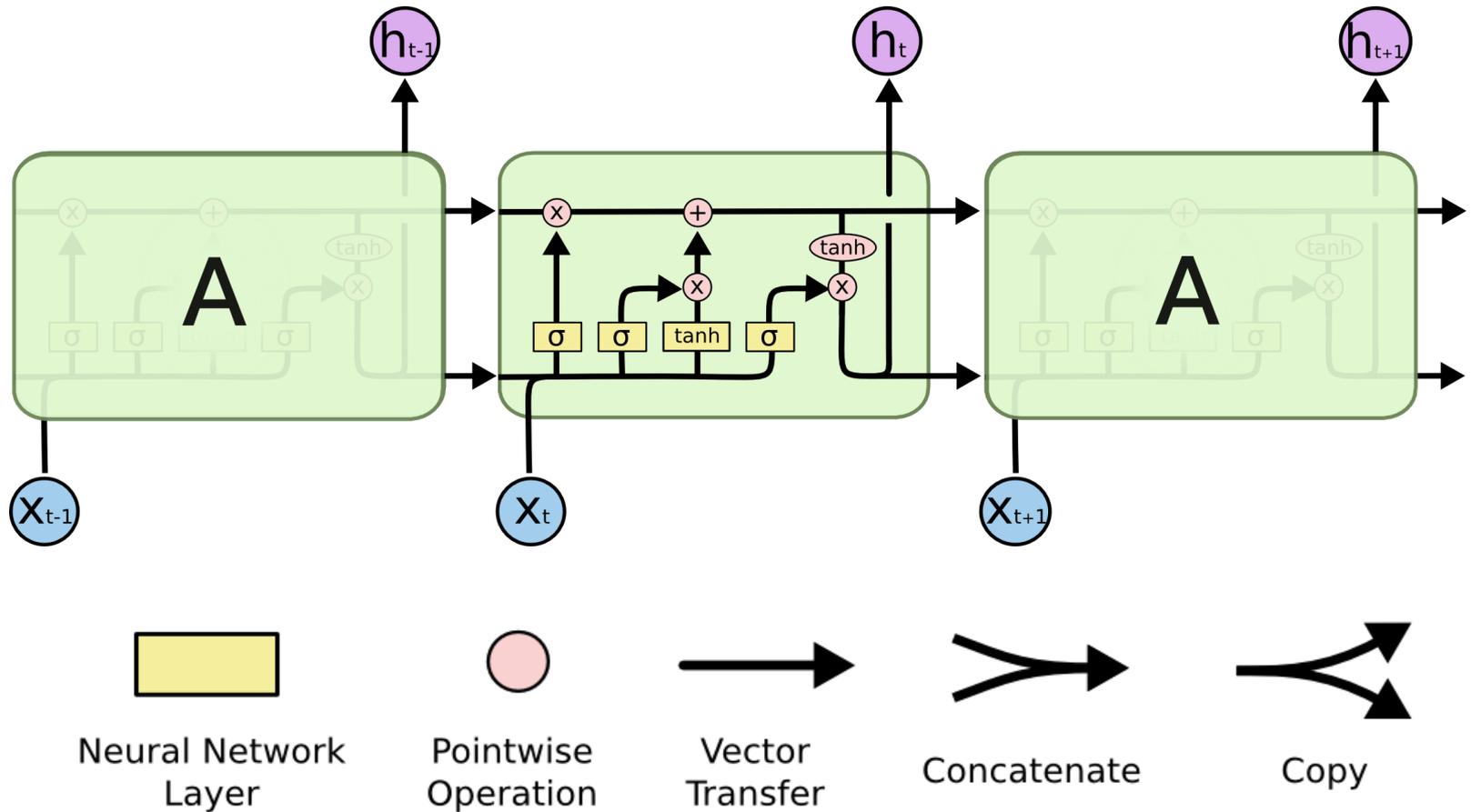
- Should we output this “bit” of information to “deeper” layers?



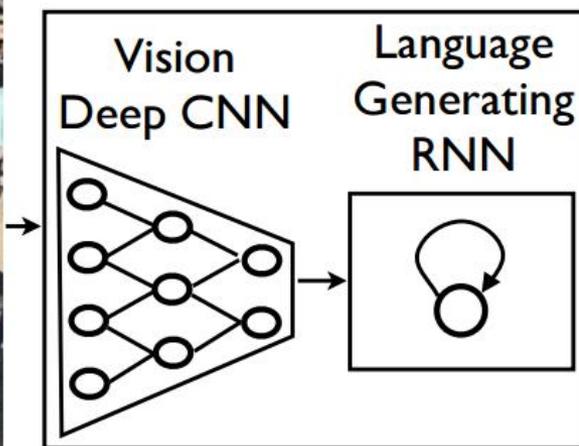
$$o_t = \sigma (W_o [h_{t-1}, x_t] + b_o)$$

$$h_t = o_t * \tanh (C_t)$$

LSTM: A pretty sophisticated cell



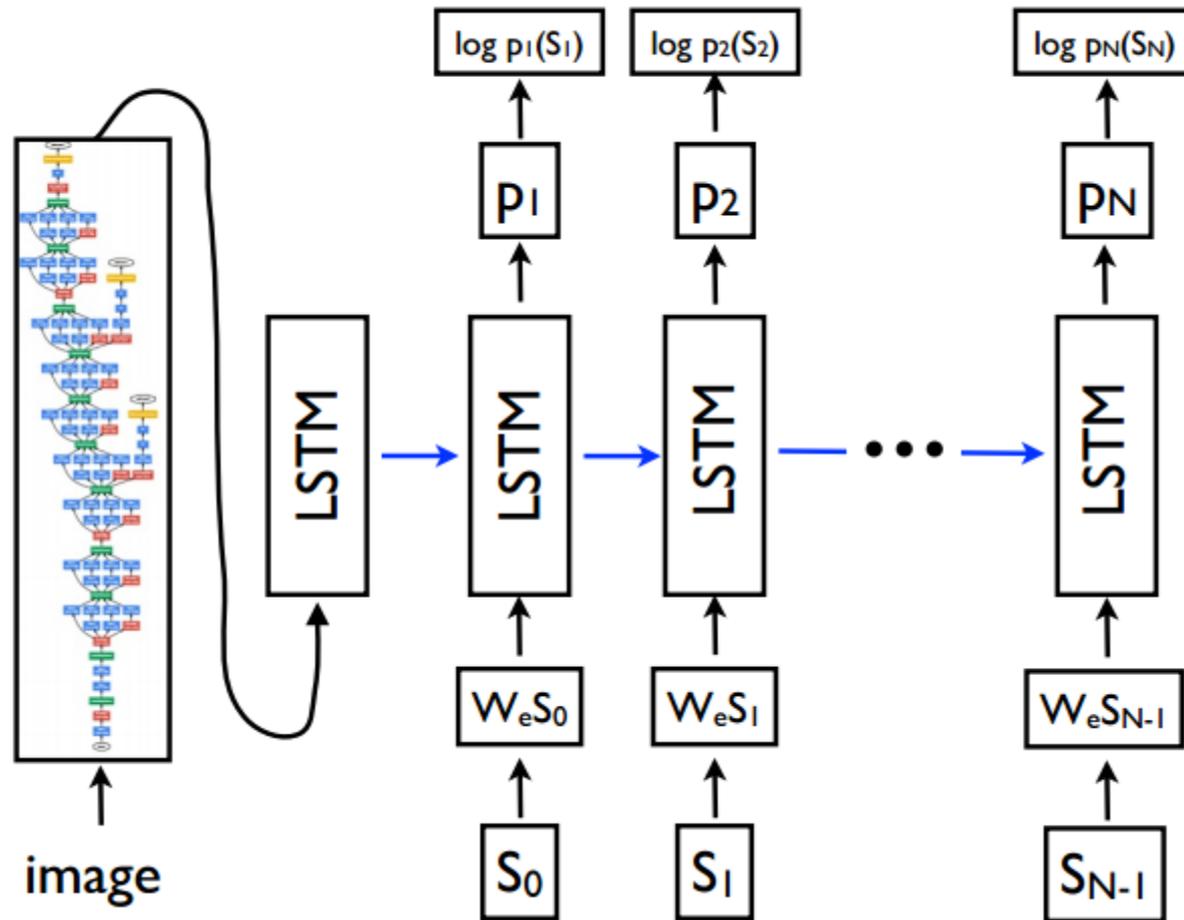
Generating image captions



A group of people shopping at an outdoor market.

There are many vegetables at the fruit stand.

Generating image captions



A person riding a motorcycle on a dirt road.



Two dogs play in the grass.



A skateboarder does a trick on a ramp.



A dog is jumping to catch a frisbee.



A group of young people playing a game of frisbee.



Two hockey players are fighting over the puck.



A little girl in a pink hat is blowing bubbles.



A refrigerator filled with lots of food and drinks.



A herd of elephants walking across a dry grass field.



A close up of a cat laying on a couch.



A red motorcycle parked on the side of the road.



A yellow school bus parked in a parking lot.



Describes without errors

Describes with minor errors

Somewhat related to the image

Unrelated to the image